

## A COMPREHENSIVE REVIEW ON DATA STREAM MINING TECHNIQUES FOR DATA CLASSIFICATION; AND FUTURE TRENDS

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### Abstract

*Data Mining is a developing interdisciplinary control managing Data Reclamation and Data Stream Mining techniques, whose subject is gathering, overseeing, processing, breaking down, and visualizing the huge volume of organized or unstructured data. Data stream mining indicates how to look at Unknown patterns from a massive amount of data over algorithms. It has experienced quick improvement with significant progress in math, statistics, data science, and computer science domains. Data streams are commonly generated by various sources such as sensor networks, social media feeds, financial transactions, online retail, network traffic, and many other applications. The gathered data could be additionally utilized for various purposes, for example, execution assessment, irregularity discovery, change identification, or issue finding of the operating systems. This data stream analysis is done using different data stream mining techniques. This paper provides a broad overview of the distinct approaches used for data stream mining. Initially, we studied the different techniques of data stream mining. Next, we discuss the different clustering and classification techniques and their benefits. Then we examine the evaluation of different data stream mining techniques results that some techniques are feasible for real-time data streams and some of not. This study provides a complete understanding of techniques and their benefits. The studies done so far need to be sufficiently exhaustive for data mining techniques, so future work is needed to assess which technique is feasible for real-time data streams.*

**Keywords:** *Data Stream Mining, Rapid Development, Classification, Clustering, D-Stream, HP Stream, ANNCAD, CDM, AWSOM, CLustream, Approximate Frequent Counts*

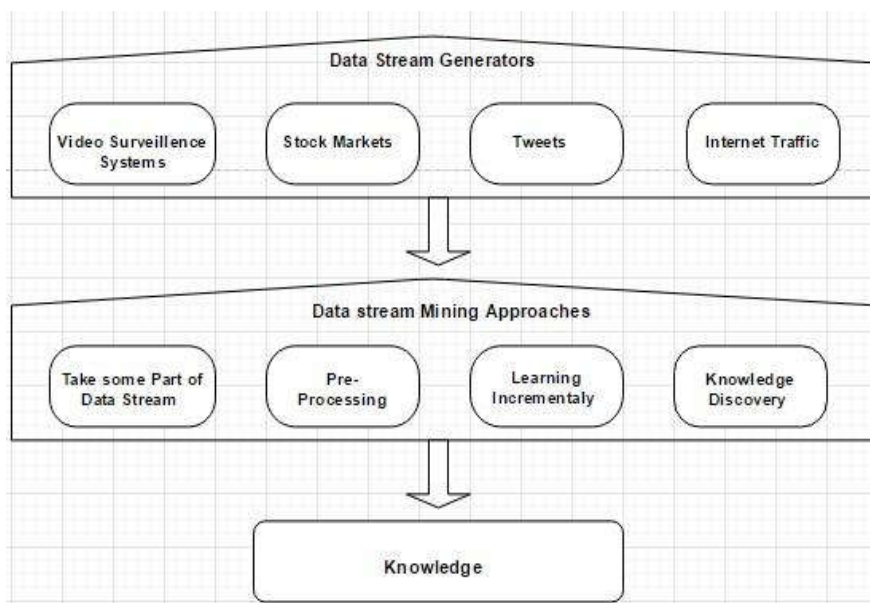
## 1. INTRODUCTION

Data streams mean data flow continuously; for example, data arrive from different sources of real-time applications such as Facebook, internet traffic, socket markets, etc. Therefore, data speed and volume are critical challenges in data stream mining [1].

Now, online applications are generating data constantly, and data is growing very fast, for a considerable amount of data is generated by applications used to start different stream data approaches. Data stream mining techniques are used to analyze vast volumes of data to find patterns required to make business decisions. In real-time making a business decision, stream data mining has become important research work and uses different areas of computer science and engineering. These techniques are challenges to processing huge amounts of data. Stream data can be trained algorithms by example that continuously huge amounts of data with high speed from different sources as shown in Figure 1.

Data stream mining is a very famous and fascinating area of research in computer science that has gotten very important in the last two decades. Although the systems of the modern era are very advanced, the hardware and software are advancing day to day for the benefit of human beings. As a result, data generation is increasing with these advanced hardware devices, like Fire detection systems in hospitals or rooms, Earth Quack detection, and flood detection. This speedily produced data is called “data streams” [2].

The transactions of debit cards, online transactions, remote sensors, scientific process, stock market, our search queries on Google Search Engine or any search engine, the phone calls in a city, the daily posts on different social platforms like Facebook, tweets, Instagram’s, whats-app, linked-in as well as the internet traffics or so many others distinct data streams. We need to carefully analyze streaming data for these kinds of real-time data streaming applications. Traditional data mining techniques still need to fulfill the rapidly growing needs of data stream mining. We have been developing new and adopting existing techniques that enable them to stay activated till yet in a streaming environment with the help of Ran-



**Figure 1:** Standard overview about data stream mining: Different applications generate different types of data streams. Using different data mining techniques to process the gathered data and convert it into valuable knowledge that supports business intelligence.

domization, approximation, and adaptation. This paper has briefly described the major strategies and techniques of data stream mining.

Data stream generators from source to data stream mining methods. Data stream mining approaches contain reprocessing, learning incrementally, and extracting valuable knowledge. Outputs of data stream mining are helpful information; it can use support to extract valuable information. The data stream mining techniques help analyze highly dimensional and rapidly changed data. Some techniques work on huge volumes of data that constantly change. Computation theory contains algorithms that solve time and space problems.

Stream data mining has recently been a favorite topic because data is increasing rapidly day. However, data streams are complex and challenging to analyze because the Data streams are imbalanced by nature. Increment Under Sampling for Data Streams (IUSDS) is a data mining technique used to balance data stream [3].

Stream data mining is an extensive application of big data. However, in traditional streams, data mining is not used to handle high-dimensional data. To solve this problem, a hybrid frame is offered for big data mining stream data. Hybrid is

used an online and offline model to organize different tasks [4]. The data stream is the proper way to handle the massive size of data that is constantly growing, and it is impossible to accumulate data in the form of memory. Data points are used where data arrives. Data streaming mining faces many challenges in real-time applications. For this purpose, different techniques have been developed. Traditionally **Online Analytical Processing OLAP** systems scan data at different times until they convert it into useful information. Due to distinctive patterns, OLAP systems need to be more sufficient for stream data mining. The primary aim is to process stream data to discover valuable knowledge in recently added data. For this purpose, it is essential to develop or modify existing techniques that handle different types of data from different sources rapidly. Basic two types of challenges when developing new data stream mining techniques. The first is to develop a fast mining approach that handles the data stream. Secondly, one is Discovering data variation and varying models in extremely dynamic data stream [5].

This paper presented a detailed study of data stream mining.

1. Data Stream Mining Challenges.
2. Classification Techniques.
3. Clustering Techniques.
4. Classification and Clustering Techniques advantages and disadvantages.
5. Data Stream Mining applications.

This article's structure is as follows: First, we have introduced a comprehensive analysis of data stream clustering and classification algorithms in section 1. secondly, the scope and objective and the challenges for data stream mining in Section 2. Third 3, some primary studies have been discussed about data stream methods/techniques in Section 4. Then we performed a brief comparison in Section 5. Some data stream mining applications have been discussed in Section 6; last but not least, we have concluded this paper in Section 7.

## 2. Challenges

In data stream mining, continuously generating a large amount of data by real-time applications introduces several challenges. These challenges arise due to the huge volume, high speed, and constant data flow in data streams. Some of the key challenges in data stream mining include:

- **Data flows fast with high speed and real-time in data streams:** Data streams are generated continuously and often at a high velocity. Data arrive rapidly, and there is a constant flow of new information. It adds to the challenge of processing the data in real-time or near real-time to extract timely insights and make prompt decisions.
- **Random access to the data stream is impossible:** Unlike traditional batch processing, where random access to data is possible as the entire dataset is available, random access in data streams is not feasible. Data streams are typically consumed sequentially; once a data point has passed, it is challenging to reaccess it. This imposes limitations on certain types of analyses and requires algorithms designed for sequential processing.
- **The massive volume of data is processed with limited memory:** Data stream mining algorithms often operate under constraints of limited memory and computational resources. Despite the high volume of data generated by data streams, the algorithms must process and analyze the data efficiently within the available memory. This necessitates using memory-efficient data structures and algorithms to effectively handle the continuous flow of data.
- **Stream data mining requires high-speed processing within a limited time:** Data stream mining requires algorithms that can analyze and extract insights from data streams in real-time or near real-time. The speed at which the algorithms process the data is crucial to keep up with the fast flow of incoming data. Timeliness is essential in data stream mining to support real-time decisionmaking and respond quickly to evolving patterns and trends.

**Table 1:** Difference between traditional data mining and stream data mining

Sr. No.	Data Parameters	Traditional Data Mining	Stream Data Mining
1	Data Types	Static	Dynamic
2	Data Length	Bound	Unbound
3	Arrival	Once	Many
4	Update speed	Slow	Fast
5	Scanning Time	Multiple	Single
6	Response Time	Soft Real Time	Hard Real Time
7	Time Space Complexity	Not Strictly	Strictly
8	Memory Usage	Unlimited	Limited
9	Result	Accurate	Approximate
10	Distributed	No	Yes

Many traditional and stream data mining challenges are shown in Table 1. One of the significant challenges to memory management over mining stream because some applications where nodes contain limited memory. One phase of data stream mining preprocessing consumed more resources. We need some lightweight techniques that provide better results

that overcome these data stream mining challenges. In the following sections, some improved data stream mining techniques are discussed.

### 3. Related work

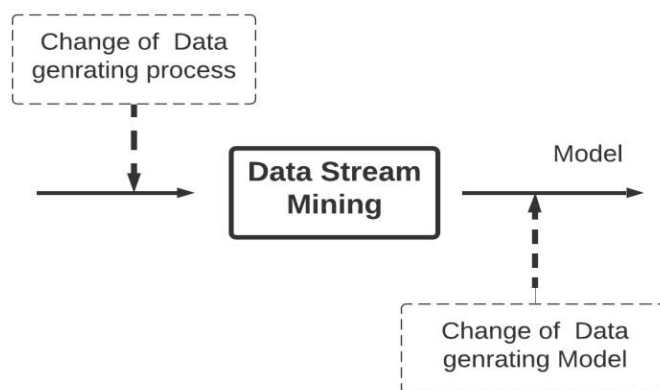
Data stream mining is focused on discovering frequency patterns for incoming data with the help of clustering and classification. Traditional methods of traditional steam data mining are needed for high results. However, traditional steam data mining methods are limited to handling huge amounts of data; for this problem, the hybrid framework is used to handle massive amounts of steam data mining. The hybrid framework contains online and offline models that handle different tasks. Different clustering and classification algorithms discover frequent patterns. Stream data mining handles big data with hybrid frameworks [6].

Clustering[7] is discovering frequent information streams with the help of algorithms. It is a grouping process in which information is partitioned into various information groups as indicated by various information qualities. This makes a separation distance between and inside components of a similar bunch. However much as could reasonably be expected, components in various groups are as extensive as expected. The grouping has a unique algorithm, for example, Stream and Clustream[7]. Based on the k-Means calculation, the stream calculation utilizes the isolating and vanquishing technique for grouping and guarantees the least blunder aggregate of squares of components in a bunch.

The classification algorithm is a managed learning algorithm, a grouping calculation can determine a learning model by learning the present preparation, And it can give expectation characterization information [8]. In the characterization issue, two primary regions of research are discussed in previous research: idea floats order and characterization dependent on the test classifier. For test characterization, numerous researchers center around this, researching test time execution and memory usage, Such as VFDT calculation [9]; DomIngos and Hulten propose it [10] in 2000 and has numerous points of interest as far as speed and exactness. Moreover, many existing calculations require preparing sets named by specialists trained and evaluated, which is not reasonable for a quick information stream, for instance, marking time and expenses. As of now, if under supervision, become familiar with a technique utilized to prepare the classifiers, with less named information accessible for the classifier.

The Mining of Data Streams has been outstanding for the most part considering that the numbers of advanced electronic contraptions have been developing dependably to satisfy the requirements of the current era. These gadgets are conveying dependably enormous volume of information streams. The nature of the information Stream is multifaceted, difficult to investigate, and mine profitably. When the data stream contains classes that are disproportion in nature, then the preparation of knowledge becomes an astoundingly phenomenal assignment. A couple of takes a gander have been passed on right now, whose fundamental goal is to get from information streams where the class balance is excitedly slanted.

Iain Brown et al [11] have examined a few structures that different of imbalanced credit scoring educational records; in any case, prudent power of the strategies is adversely affected.



**Figure 2:** Diagram for detecting changes in data stream.

Victoria Lopez et al [12] utilizes an Iterative Instance Adjustment for Imbalanced Domains. Their learning strategy contains three key endeavors: a customized installment procedure, a developmental improvement of the organizing of the examples, and a confirmation of the most authority models for each class.

Nele Verbiest Et al [13] proposed an improved structured minority oversampling system SMOTE in the closeness of class mayhem. Their way of thinking cleans the information before applying SMOTE, so the possibility of the made occasions is better. It cleans the information after applying SMOTE, with a definitive target that cases astounding or presented by SMOTE that gravely fit in the new data set is cleared.

This research is focused on Big data which contains three parts volume, velocity, and variety. The data stream processing area has long timed two-folded speed and volume. Big data is the result of social media and produces extensive extraordinary data. Recently, streaming techniques have been presented as this emerging address. Many factors affect big data; our world is a critical success factor in rapidly changing and changing variables. The volume of the data is growing at a 50 per expected rate in a year. In all honesty, the online data-spilling process is the fundamental method for managing massive data, tremendous volume, colossal speed, and three unmistakable features. Spilling data is fleeting data in nature. Despite the transient, the spouting data fuses neighborhood features. One of the problems facing data entry and mining is

the nature of the change streaming data shows to identify patterns that change over time. Continuous distributed monitoring model that deals with recently been suggested to deal with streaming data from Multilevel. These models contain observers, but a single observer oversees a single series. This model is a used screen system, for example, sensor systems, mutual organizations, and ISP systems regarding spilling. The way toward change recognition information is to partition the procedure into various parts, which shows stream. The change detection method contains two tasks: Localization of change and change detection. Notwithstanding the discovery of progress, the restriction of changes decides the area of the change. Change detection problem is the readable view of the detection issues in data. Streaming data contains basic features. First of all, the data is constantly reached. Second, streaming data prepares for extra time. Third, streaming data could be quieter and better. Ahead, timely interference is important. Change detection: Drift detection focuses on supervised learning and label data, and change detection deals with supervised and unsupervised learning. Different methods are used to detect change streams that can be classified using a data stream model, data characteristics, completeness of statistics information, the velocity of data change, speed of response, decision-making methodology, and stream processing methodology. There are two design modes to promote sewage songs of detection of streaming data. Two methodologies are used for changing detection algorithms in the data stream, existing change detection algorithms data stream and new changes detected algorithm streaming data. After reaching a large stage, big data techniques and detection of change in the detection of future works are expected to choose such applicable data processing tools, effectively ranked detection, local making and rating changes[14].

Mining hot topics from Twitter streams have attracted much attention in recent years. Data mining from Twitter streams has been a favorite topic recently. Traditional hot topic mining on the internet w based on the clustering technique. Specifically, this research uses the Frequent Pattern stream mining algorithm (i.e., FP-stream) to detect hot topics from Twitter streams[15].

Twitter information is identified with rehashed designs regarding the mining; thus, frequently, the consequences of the term set are hot Twitter points. Hot Topics Twitter may appear on the subject function for a good acceptance. The Hot topic detection system is shown in figure 3 [15].

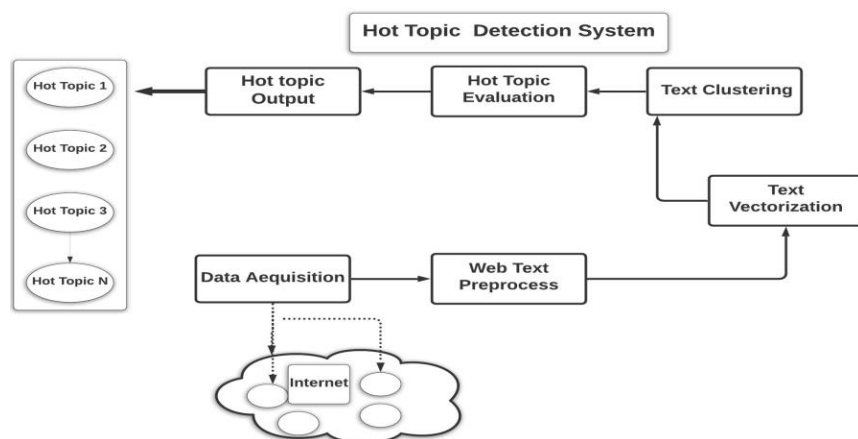


Figure 3: Diagram show hot topic detection system.

Table 2: Capabilities of Data Stream Clustering Algorithms

Sr. No.	Algorithm	BoundedMemory	Single-pass	Real-timeResponse	Concept-driftAdaptation	Concept-driftClassification	High-dimensionalData
1	STREAM [O'Callaghan et al. 2002]	✓	✓				
2	CluStream [Aggarwal et al. 2003]	✓	✓	✓			
3	HPStream [Aggarwal et al. 2004]	✓	✓	✓			✓
4	SWClustering [Zhou et al. 2008]	✓	✓	✓			
5	E-Stream[Udoimmanetanakit et al. 2007]	✓	✓	✓	✓		
6	RepStream [Lhr and Lazarescu 2009]	✓	✓				
7	OpticsStream [Tasoulis et al. 2007]	✓	✓	✓			
8	Den-Stream [Cao et al. 2006]	✓	✓	✓			
9	IncPreDeCon [Kriegel et al. 2011]	✓	✓				✓
10	D-Stream [Chen and Tu 2007]	✓	✓	✓			
11	MR-Stream [Wan et al. 2009]	✓	✓	✓			
12	Cell-Tree [Park and Lee 2004]	✓	✓		✓		

13	Cell*TYee [Park and Lee 2007)	✓ ✓ ✓ ✓	
14	XWAVE [Guha et al. 2004]	✓ ✓ ✓ ✓	
15	SWEM [Dang et al. 2009]	✓ ✓ ✓ ✓	
16	GCPSOM [Smith and Alahakoon 2009]	✓ ✓	✓

This research describes and evaluates OLIN, an online classification system; it adjusts automatically to the amount of concept drifts in stream data mining by the dynamic set size of the training window. OLIN is applied on recent changes in stream data arbitrary period. OLIN provides higher accuracy than fixed size sliding window. OLIN monitors online receiving continuous stream data. OLIN predicts correct classes of receiving stream data by using current classification. OLIN provides correct classification[16].

Hai-Long Nguyen et al. [17] provides a brief comparison based on mean average precision (mAP) and frame per second (FPS) of all clustering algorithms used for data stream mining. The comparison is based on some factors, bounded memory, single-pass, and concept drift adaption, as shown in Table 2.

Data stream mining has been very famous and an open challenge in recent years. Many techniques have been proposed in this area of research. The "Decision Tree" trendy ending 80's and early 90's ID3 and CART are the most effective procedures in facts stream mining. The biggest problem is to certify with the significant probability that choosing the attributes of N examples is the same as choosing the attributes from infinite examples. Hundreds of researches were carried out to solve this kind of problem. Among this research, "Hoeffding's Trees Algorithm" was a famous tool for mining data streams. It routines Hoeffding's sure for selecting the minimum figure of samples required on a knot to choose a piercing element. Information gain or Gini Index is similar to Hoeffding's bound descriptive in the literature used for evaluation function.

#### 4. Data Streaming Methods

Stream data mining is focused on discovering frequently coming data with the help of clustering and classification. Traditional methods of old steam data mining are needed for extraordinary. Some classification and clustering techniques are used to detect frequency patterns with pre-processing. Some classification and clustering techniques are used to detect frequency patterns without pre-processing.

##### 4.1. Clustering

Clustering is the splitting and gathering of an individual set of perceptions allowing the resemblances of their characteristics. Over the years, various data stream cluster analysis strategies with the least time and memory required have been offered. These calculations typically require just one go through the data to change the following idea floats. Following are some prominent algorithms.

The Local Search and Stream algorithm combines two techniques, Stream and Local Search, and is primarily used for incremental learning in data stream clustering. The algorithm operates repetitively on different portions of data. The Stream algorithm identifies the scope sample, representing a subset of the data stream. This sample is then processed using the Local Search algorithm. The built-in equation is applied to handle the computational load if the sample size is large. The Local Search algorithm focuses on improving the cluster centers generated in previous iterations. It applies search techniques to refine the cluster centers and enhance the clustering quality [18]. Here are the characteristics of the Local Search and Stream algorithm:

- **Mining Method:** The algorithm employs a clustering technique specifically designed for K median. K Medians is a variation of the K-means clustering algorithm that uses medians to represent the cluster centers.
- **Advantages:** One of the advantages of the Local Search and Stream algorithm is its ability to perform incremental learning. Incremental learning allows the algorithm to adapt to new data without reprocessing the entire dataset, which is useful for scenarios where data arrives continuously or in streams.
- **Disadvantages:** However, a drawback of this algorithm is that it may not provide high-quality clustering results or high accuracy compared to other clustering techniques. It is important to consider the specific requirements and characteristics of the data before choosing this algorithm For clustering tasks.

##### 4.1.1. StreamSW Algorithm

StreamSW approach embraces a disconnected online structure for performing clustering on flowing information on a sliding window. The online segment of streamSW ceaselessly peruses an object over a sliding window and adds it to an as of now existing micro-group or guides for the grid cell. The streamSW approach utilizes an upgraded DBSCAN technique in the disconnected component to shape the last large-scale groups on request by the user. DB-SCAN creates many starting micro-group scale clusters before the execution of the streamSW. The two stages of the streamSW technique in the online part are the merging and mapping stage and the pruning stage. Consolidating and mapping phase, the Algorithm displays the combining and planning phase of streamSW. At the point where another point p shows up at timestamp etc., the procedure for consolidating and planning the fact of the matter is portrayed as follows.[19]

- From the start, StreamSW discovered the nearest microgroup cp out of p.
- The calculation attempts to consolidate p with cp.
- If rp, the recently figured span of cp, is not precisely or equal to the most extreme range E, p is converged into cp at that point.
- Else, p is planned into the matrix g, and afterward, the CV of the grid is updated.

- If  $g$  is a dense network, we develop another  $p$ -small scale bunch from the lattice  $g$  at that point.
- The related framework  $g$  of the new  $p$ -microcluster is deleted.

**Offline Phase:** A changed DBSCAN technique is received to shape the last microclusters in the disconnected segment. In streamSW, the rundown of the flowing information is kept up in the method of  $p$ -microclusters. In any case, to make the last subjective shape clusters, an adjusted DBSCAN algorithm is executed on the  $p$ -smaller scale clusters by checking every  $p$ -smaller scale bunch as a virtual point set at focus  $c$  with  $w$  weight.[19]

**Pruning Phase:** The pruning system of streamSW appears in Algorithm. Lapsed lattices, inadequate networks, and anomaly bunches are evacuated in this stage. We discover and erase lapsed lattices dependent on the time stamps. If the timestamp of the framework is not in the  $N$ -length sliding window, at that point, it is treated as a lapsed lattice, and it will be disposed of from the grid list. Inadequate lattices, what is more, anomaly bunches are erased from the brace rundown and  $p$ -miniaturized scale bunch list separately by taking a gander at their loads intermittently.[19]

**Experimental Results** We have actualized our stream SW in an R-expansion, named a stream, a stretched model for execution, and tried different things with different data mining algorithms. We contrast StreamSW and previous methods such as MCDA Stream, SD Stream, and CluStream. Similar to SDStream, the boundaries for the streamSW algorithm were set as follows: anomaly limit[19]

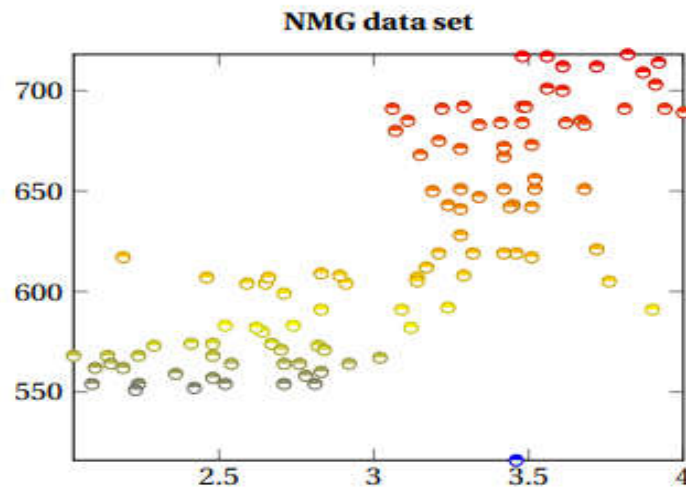
$$\beta = 0.2, \mu = 10, \epsilon = 16 \quad (1)$$

For MCDA Stream

$$\lambda = 0.5 \quad (2)$$

For CluStream we choose  $k=5$  clusters.

**Data Sets:** Information sets: To assess the presentation of streamSW and another algorithm. We utilize both real data just as synthetic informational sets. Engineered informational index: We have investigated with NMG (Noisy Mixture of Gaussians) informational collection produced from the stream. Test components for NMG informational index are shown in the graph. It has 2-d information objects with 5 percent noisy data[19].



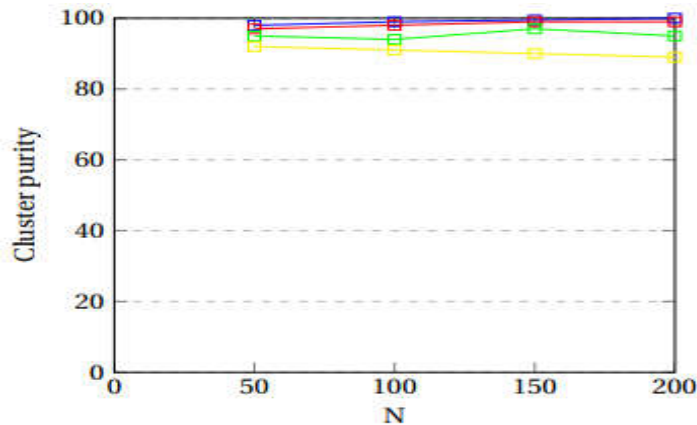
**Realdataset:** To evaluate StreamSW execution on true information, pick a data set called NID (Network et al.). NID is a broadly utilized information set available from the UCI ML vault. It consists of LAN-organized records with much information. Each record has 42 qualities, of which 34 are consistent at-tributes, and 7 are clear-cut traits and class attributes. We measured every one of the 34 constant properties to assess our algorithm. The informational index is changed into the information stream by measuring the request for input information as the request for spilling[19].

### Clustering Quality Evaluation:

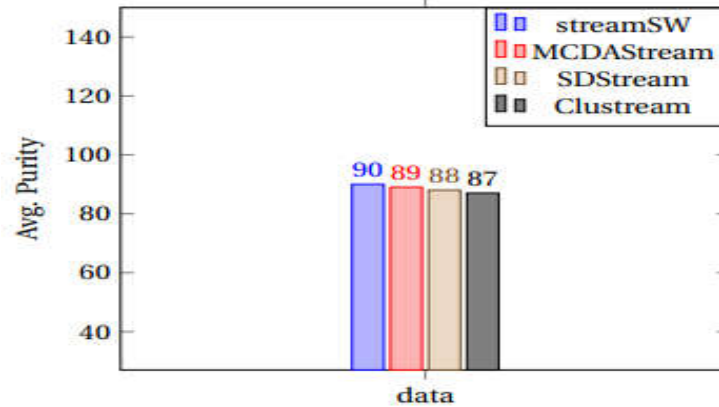
In the evaluation of the clustering quality of the StreamSW algorithm, the authors used a specific assessment criterion called purity. Purity is a measure that evaluates how well the clusters generated by an algorithm match the ground truth or known class labels of the data. In the evaluation, the authors compared the clustering purity results of StreamSW with three other algorithms: MCDASStream, SDStream, and CluStream. They evaluated the NMG dataset. According to the results in the figure mentioned in the reference (not available here), StreamSW achieved a clustering purity of more than 98 percent throughout the entire period. This indicates that the clusters produced by StreamSW had a high degree of agreement with the ground truth labels in the dataset. The authors highlight that StreamSW outperformed the other compared methodologies regarding clustering purity. It is important to note that in the evaluation, the sliding window ( $N$ ) size was set to 4, but further details or context regarding the dataset and the specific evaluation methodology are not provided in the given information[19].

### Quality comparison of the NMG data set, N=4

We have additionally evaluated the grouping nature of StreamSW on NID informational collection. The graph shows the bunching immaculateness results for NID informational collection. It is seen that StreamSW has high bunching quality than MCDASStream, SDStream, and CluStream. The normal virtue of StreamSW is higher than 98 percent.



### Clustering Purity of StreamSW on NID data set

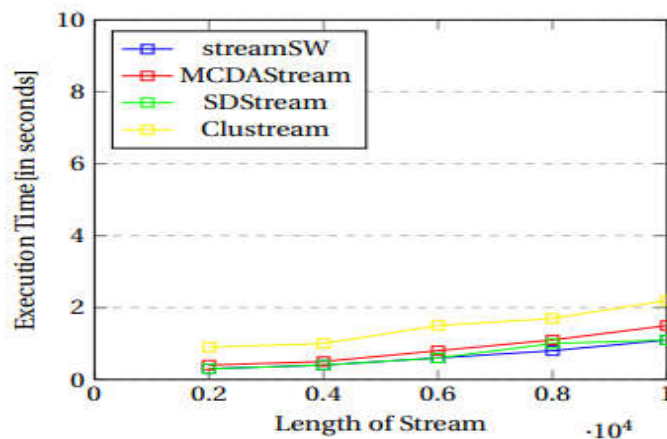


### Execution Time:

The presentation of StreamSW is assessed by the executing time. We utilize NID informational index to evaluate the proficiency of StreamSW over the MCDASStream, SDStream, and CluStream. The data stream speediness influences the running time of StreamSW. The figure below shows the running time for the NID informational collection. We notice that the running time of StreamSW and other existing methodologies develop straightly as the stream continues over sliding windows. StreamSW has a lower running time contrasted with SDStream and CluStream. The online period of StreamSW utilizes network thought to plan the anomaly information focuses.

So the running time of StreamSW is lower than SDStream and CluStream. The time-multifaceted nature of StreamSW is decreased by receiving network-based grouping.

### Execution time Vs Length of stream



- **Mining Method:-** This is clustering technique useful for K Medians.
- **Advantages:-** It can learn Incremental learning method.
- **Disadvantages:-** It does not provide good clustering quality and accuracy.



### 4.1.2. HECES Algorithm

The HECES process is used for clustering data streams. Its inputs are the stream  $S = \{x_1, x_2, \dots, x_i, \dots, x_{ng}\}$ , the size of sliding window  $D$  and the grid-Cell size  $w$ . Its output is a set of hyper-elliptical clusters [20].

**HECES Algorithm Steps:** The HECES calculation is a two-stage bunching method to develop an information stream. Stage 1 comprises Step 1, whereas Stage 2 comprises Steps 2 to 4. During the main stage, it segments the information space into  $d$ -dimensional lattices. In contrast, the subsequent stage produces the last groups utilizing the measurable outline gathered during the primary period of the HECES calculation [20].

**Step 1:** In the primary stage, at time  $t$  at  $\frac{1}{4} 0$ , we introduce the void grid list  $G$ . Then gathering of each information datum, matrix Cell ( $g_i$ ) is resolved which have it. Whenever  $g_i$  isn't in the current grid list, we embed  $g_i$  into grid list and introduce the appropriation measurements of  $g_i$  (Definition 4) [20].

**Step 2:** After accepting  $D$  protests, the subsequent stage begins. From the outset, the unfilled cells and cells having cardinality not as much as  $p$  are expelled from the  $G$ , where  $p \frac{1}{4} 1G rG$ . Group  $G$  is refreshed, as shown in line 11. Hyper-ellipsoid is fitted on the information in every network Cell  $g$ , with the end goal that the limit of the ellipsoid covers, at any rate, 95 percent of the information in  $g$ . Due to this reason, we need to compute the non-solitary covariance of information inside  $g$  utilizing the shrinkage technique. The hyper-ellipsoids on every network Cell are presently the underlying bunches [20].

**Step 3:** Mahalanobis separation among focuses of every recently developed hyper-ellipsoid is determined. The last groups are gotten by blending the ellipsoids having a separation between their focuses, not a limited separation.

**Step 4:** The repetitive ellipsoids in each bunch are evacuated if the separation between their focuses is not precisely the edge as appeared in Algorithm. The last groups have the shape and direction which speak to the current information [20].

**Experimental Evaluation** In this section, we present the assessment of the HECES algorithm as of late proposed grouping calculations. We implemented calculation in MATLAB R2012b when we used CluStream and Den-Stream execution accessible in Massive Online Analysis (MOA1). We played out all the experimentation on Dell Inspiron 1440 on Windows 8, 32 pieces with 2GB memory. Assessment is performed after getting  $D$  objects, where every item is considered a period unit. In this section, first, we depict the data sets and, afterward, assessment results used to assess the HECES calculation. At long last, de followed it investigates simple and engineered data sets talked about [20].

**Datasets** The dataset utilized for assessment is an arbitrary Radial Basis Capacity (RBF) manufactured dataset created by MOA, which has been generally utilized for assessing grouping techniques for advancing data streams. The prominent advantage of utilizing manufactured data is that we can produce datasets of self-assertive sizes and can, without much of a stretch, change the material boundaries of the learning procedure. We reduce three manufactured datasets, RBF5, RBF10, and RBF15, with 5, 10, furthermore, and 15 quantitative qualities separately. These datasets comprise five bunches and one million records. We produce three 2D manufactured datasets, DS1, DS2, and DS3, which appeared in Figure 4. Every one of them contains 10,000 focuses and four bunches. These data sets are joined multiple times by haphazardly picking one of them to create an Evolving Data Stream (EDS). Henceforth, the complete length of the EDS data is 100,000 [20]. The second actual data set is High-Speed Rail data (HSR) gathered by sensors observing vibration, weight, and commotion to guarantee the well-being of the train. This genuine data comprises 15 numeric traits and an aggregate of 179,113 items having 1–3 bunches for various estimations of  $D$ . An outline of genuine and engineered datasets is given in Table 3.

**Evaluation of HECES for Synthetic Datasets** In the accompanying, we contrast our algorithm and two notable stream

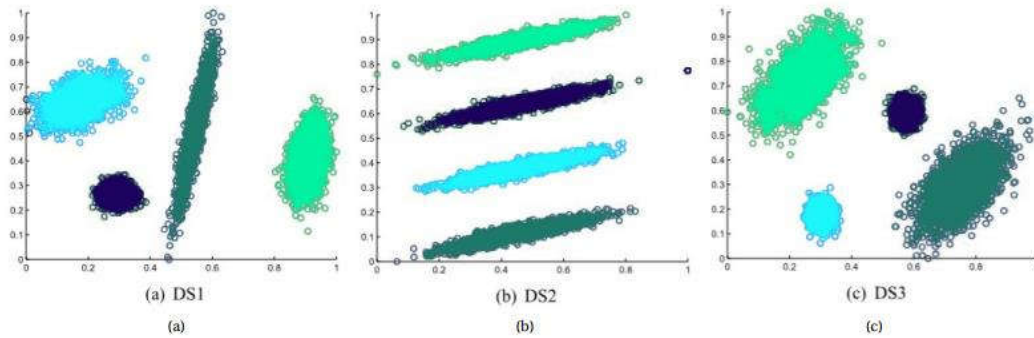
**Table 3:** Comparison Evaluation of HECES for Synthetic Datasets

Sr. No.	Datasets	Number of Objects	Number of Attributes	Number of Classes
1	RBF5	1000000	5	5
2	RBF10	1000000	10	5
3	RBF15	1000000	15	5
4	DS1	10000	2	4
5	DS2	10000	2	4
6	DS3	10000	2	4
7	EDS	100000	2	4
8	Forest Cover Type	581012	10	3-7
9	High Speed Rail	179113	15	1-3

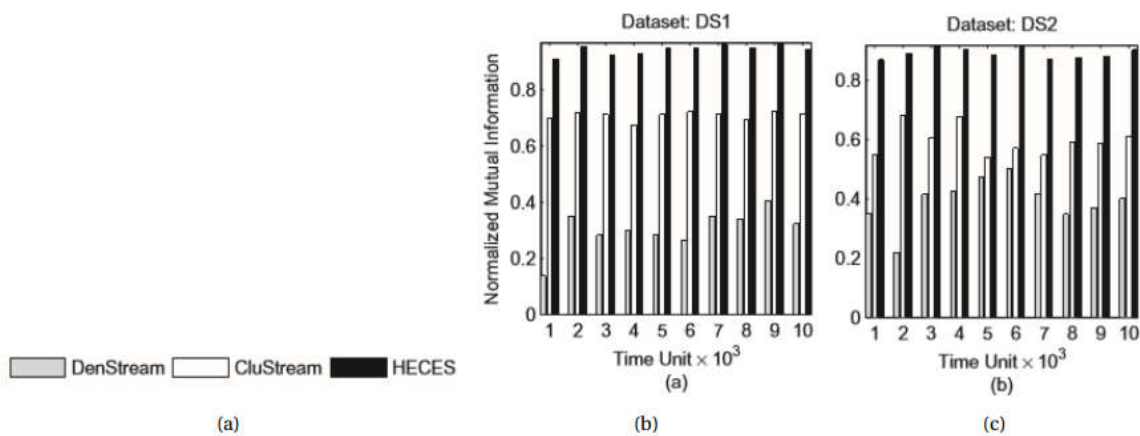
bunching calculations named as DenStream and CluStream. Notice that we attempt different estimations of parameters for Den Stream and CluStream. Except if in any case mentioned, the calculation boundaries in our investigations for Den-Stream are set at  $MinPts \frac{1}{4} 10$  and  $Eps \frac{1}{4} 0:01$ ;  $b \frac{1}{4} 0:01$  and  $l \frac{1}{4} 1$ , while for CluStream's boundaries are set at a maximum number of kernels=100 and Kernel-Radi-factor=2. After numerous tests, we take the estimation of  $f \frac{1}{4} 0:25$  for the HECES

calculation. Point-by-point tests demonstrated that the HECES cloud keeps high bunching exactness results and has a more robust adaptability to deal with enormous scope data sets as shown in Figure5(a-c)[20].

Detailed experiments proved that the HECES cloud keeps high clustering accuracy results and has a more robust adaptability to handle large-scale data sets[20].



**Figure 4:** These figures is basically showing the different data sets on said labels. In (a) DS1, (b) DS2, (c) shows the DS3.



**Figure 5:** These figures is basically showing the different data sets on said labels. In (a) DS1, and (b) shows DS2.

#### 4.1.3. DUCstream

DUCstream algorithm is utilized for bunching information streams. It is a solitary pass algorithm equipped for recognizing evolving clusters but requires little memory and calculation time. In brief, we will locate the thick units and group these units. First, we consider what units should be kept up along these lines due to the idea of thick neighborhood units [21].

**Framework:** We sum up our stream grouping algorithm. We allude to this algorithm as DUCstream (Dense et al. for information stream). The information structures used in the algorithm include  $L$ , the neighborhood thick units table;  $Q_a$ , the additional thick units id list;  $Q_d$ , the erased thick units list;  $R_i$ , the bunching result  $c_1, \dots, c_s$  at time stamp  $i$ . The essential parts of this system involve the following:

**Map and Maintain( $X_i, L$ ):** This system maps each datapoint in  $X_i$  into the comparing unit. For one of these units,  $u$ , on the off chance that it is in  $L$ , update the comparing thing, other-wise if  $u$  is a thick neighborhood unit, embed it into  $L$ . After that, scan  $L$  once and choose  $Q_a$  and  $Q_d$  [21].

**Create Clusters( $Q$ ):** We utilize a profundity first hunt algorithm to make groups as depicted. They distinguish the bunches as the associated parts of the chart whose vertices speak to thick units and whose edges compare to the regular appearances between two vertices [21].

**DUCstream Algorithm:** Input: Data chunks  $X_1, \dots, X_{21}, \dots, X_n$  Output: Clustering results  $(R_1, R_2)$  Method:

1. Create a new empty table  $L$ ;
2.  $(L, Q_a, Q_d) = \text{map and maintain}(X_i, L)$ ;
3.  $R_1 = \text{create clusters}(Q_a)$ ;
4.  $i = 2$ ;
5. Repeat until the end of the data stream (a)  $(L, Q_a, Q_d) = \text{map and maintain}(X_i, L)$ ;
- (b)  $R_i = \text{update clusters}(R_{i-1}, Q_a, Q_d)$ ;
- (c)  $i = i + 1$ ;

**Update Clusters( $R_{i-1}, Q_a, Q_d$ ):** We get the clustering result  $R_i$  in an incremental manner stated as follows.

For each additional thick unit  $u$ , one of the following happens:

1. Creation: If  $u$  has no regular face with any old thick units, another group is made containing  $u$ ; Absorption: There exists one old thick unit  $u$  to such an extent that  $u$  has a regular face with  $u$ , at that point ingest  $u$  into the bunch  $u$  is in;
2. Mergence: There exist various old thick units  $w_1, w_2, \dots, w_k (k > 1)$  that have basic countenances with  $u$ , at that point blend the groups these thick units have a place with. Assimilate  $u$  into the new bunch. For each erased thick unit  $u$ , assume it is contained in bunch  $c$ , we can recognize the accompanying cases:
3. Removal: If there are no other thick units in  $c$ , for example, the group gets unfilled in the wake of erasing  $u$ , we expel this bunch;
4. Reduction: All other thick units in  $c$  are associated with one another; at that point, erase  $u$  from  $c$ ;
5. Split: All other thick units in  $c$  are not associated with one another; this prompts the split of bunch  $c$ . Subsequent to preparing all the units in  $Q_a, Q_d$ , we can acquire the new bunching outcome  $R_i$ [21].

The informational collection is KDD'99 Intrusion Detection Data, divided into pieces, each comprising 1K focuses. We first look at the time unpredictability of DUCstream contrasted and the pattern strategies STREAM and CluStream. DUCstream keeps up the neighborhood's thick units, and current bunching brings about primary memory. Since the bunching results, spoken to by clustering bits, cost next to no space; we monitor the quantity of nearby thick units to screen the memory use. Figure 6(a-c) exhibits that a consistent state is reached after a specific time concerning the number of thick neighborhood units. In general, the algorithm requires an insignificant measure of memory when the information stream size turns out to be sufficiently huge[21].

At that point, we contrast DUCstream, STREAM, and CluStream utilizing the estimation SSQ, the whole of square separation. Figure 6(a-c) shows that the grouping nature of DUCstream is better than that of STREAM since we catch the attributes of bunches all the more, definitely utilizing the dense units contrasted and just keeping up  $k$  focuses. CluStream performs better when the skyline is miniature; however, the precision will generally be lower when the skyline expands [21].

#### 4.1.4. E-Stream

E-Stream is a data stream clustering method that supports the following five types of development in gushing information: commencing of a new bunch, Disappearance of an old bunch, separation of a large group, exchange of two comparative bunches, and change in the making of the group itself. It utilizes a blurring group structure with a histogram to surmise the spilling information. Even though its performance is better than the HP Stream algorithm, it requires many boundaries to be determined by the client[22].

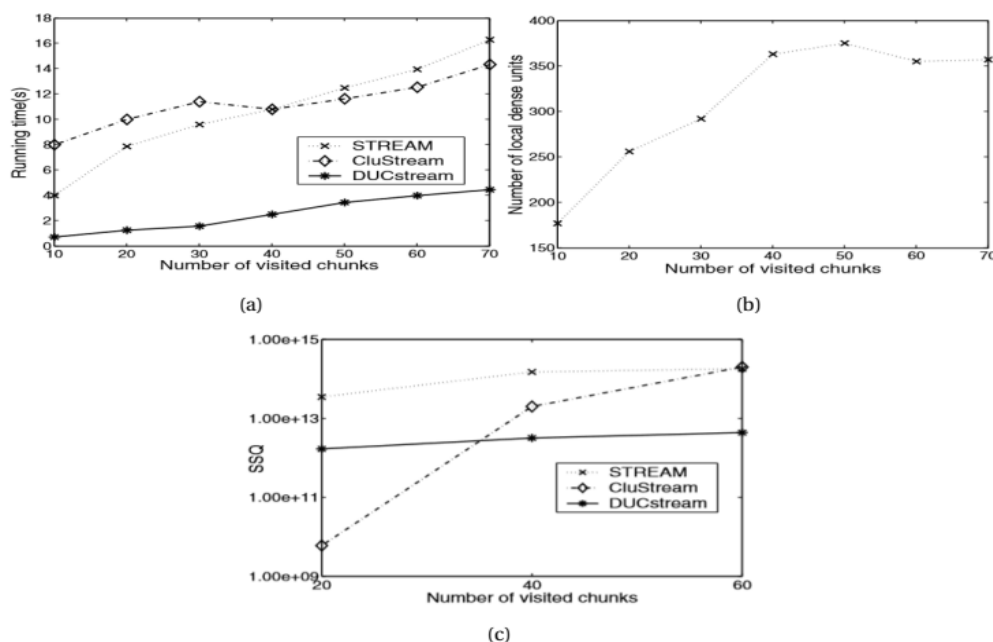
**Algorithm:** Following is the list of notations used in our pseudocode[22].

FCH = Number of current clusters.

FCHi.W = Its cluster weight.

FCHi.sd = The  $i$ th clusters standard deviation.

S = Pair of the split cluster.



**Figure 6:** These figures is basically showing the different variation data sets on said labels. In (a) Running Time, (b) shows the memory usage and (c) shows the quality comparison.

E-Stream is the essential calculation. In line 1 of figure 7, the calculation starts by recuperating another data point. Line 2 of figure 7 obscures all groups and eradicates those lacking weight. Line 3 of figure 7 plays out a histogram examination and bundle split. By then, line 4 checks for cover gatherings and combinations them. Line 5 of figure 7 checks the number of groups and associations the closest matches if the pack count surpasses the breaking point. Line 6 of figure 7 checks all bundles whether their status is dynamic. Lines 7-10 in figure 7, find the closest gathering to the moving toward information point. If the partition is not as much as the range factor, by then, the fact of the matter is apportioned to the bundle, else it is an isolated data point. The stream of control then returns to the top of the calculation and waits for new information points[22].

**Fading All** The algorithm blurs all things considered and erases the bunches whose weight is not as much as evacuate limit[22]. The algorithm is shown in figure 8.

**Check Split** is utilized to confirm the parting rules in each group utilizing the histogram. If a parting point is found in any bunch, at that point, it is part. Furthermore, store the record sets of the split group in S[22]. The algorithm is shown in figure 8.

**Check Merge** is an algorithm for blending sets of comparable bunches. This algorithm checks each pair of groups and figures the bunch separation. If the separation is not precisely consolidated limit and the blended pair is not in S at that point, combine the pair[22] as shown in figure 9.

```

Algorithm E-Stream
1  retrieve new data  $X_i$ 
2  FadingAll
3  CheckSplit
4  MergeOverlapCluster
5  LimitMaximumCluster
6  FlagActiveCluster
7  ( $minDistance, index$ )  $\leftarrow$  FindClosestCluster
8  if  $minDistance < radius\_factor$ 
9    add  $x_i$  to  $FCH_{index}$ 
10 else
11   create new FCH from  $X_i$ 
12 waiting for new data

```

**Figure 7:** E-Stream, stream clustering algorithm [22]

**Limit Maximum Cluster** is utilized to restrain the number of groups. This algorithm checks whether the quantity of bunches is not more prominent than the most incredible group (an info boundary); on the off chance that it surpasses, at that point, the nearest pair of groups is converged until the number of outstanding bunches is not exactly or equivalent to the edge[22]. The algorithm is shown in figure 9.

**Flag Active Cluster** checks the current dynamic group. If the heaviness of any bunch is more noteworthy or equivalent to the dynamic edge, it is hailed as a functional group. Something else, the banner is cleared[22]. The algorithm is shown in figure 10.

**Find Closes Cluster** is utilized to discover the separation and record of the nearest dynamic bunch for an approaching information point as shown in figure 10.

<pre> <b>Algorithm FadingAll</b> for <math>i \leftarrow 1</math> to <math> FCH </math>   fading <math>FCH_i</math>   if <math>FCH_i.W &lt; fade\_threshold</math>     delete <math>FCH_i</math> </pre>	<pre> <b>Algorithm CheckSplit</b> for <math>i \leftarrow 1</math> to <math> FCH </math>   for <math>j \leftarrow 1</math> to <math>d</math>     if <math>FCH_{ij}</math> have split point       split <math>FCH_i</math>       <math>S \leftarrow S \cup \{(i,  FCH )\}</math> </pre>
--	---

**Figure 8:** Fading All and Check Split algorithms

<p><b>Algorithm MergeOverlapCluster</b></p> <pre> for i ← 1 to  FCH    for j ← i + 1 to  FCH      overlap[i,j] ← dist(FCH<sub>i</sub>,FCH<sub>j</sub>)     m ← merge_threshold     if overlap[i,j] &gt; m*(FCH<sub>i</sub>.sd+FCH<sub>j</sub>.sd)       if (i, j) not in S         merge(FCH<sub>i</sub>, FCH<sub>j</sub>) </pre>	<p><b>Algorithm LimitMaximumCluster</b></p> <pre> while  FCH  &gt; maximum_cluster   for i ← 1 to  FCH      for j ← i + 1 to  FCH        dist[i,j] ← dist(FCH<sub>i</sub>, FCH<sub>j</sub>)     (first, second) ← argmin<sub>(i,j)</sub>(dist[i,j])     merge(FCH<sub>first</sub>, FCH<sub>second</sub>) </pre>
---	---

**Figure 9:** Merge Overlap Cluster and Limit Maximum Cluster algorithms

<p><b>Algorithm FlagActiveCluster</b></p> <pre> for i ← 1 to  FCH    if FCH<sub>i</sub>.W ≥ active_threshold     flag FCH<sub>i</sub> as active cluster   else     remove flag from FCH<sub>i</sub> </pre>	<p><b>Algorithm FindClosestCluster</b></p> <pre> for i ← 1 to  FCH    if FCH<sub>i</sub> is active cluster     dist[i] ← dist(FCH<sub>i</sub>, x<sub>i</sub>)   (minDistance, i) ← min(dist[i]) return (minDistance, i) </pre>
--	--

**Figure 10:** Flag Active Cluster and Find Closest Cluster Algorithms

We tried the algorithm utilizing a manufactured dataset comprising two measurements and 8,000 information focuses [22]. This information changes the conduct of bunches after some time. We can fragment it into eight stretches as follows:

1. At first, there are four bunches in a consistent state. Information point from 1 to 1600.
2. The fifth bunch shows up at position (15, 6)—information point from 1601 to 2600.
3. The first cluster vanishes—information point from 2601 to 3400.
4. Fourth group swells—information point from 3401 to 4200.
5. The second and fifth bunch draw nearer—information point from 4201 to 5000.
6. The second and fifth are converged into a more excellent bunch—information points from 5001 to 5600.
7. A sixth bunch is a part of the third group. Information point from 5601 – 6400.
8. Each bunch is in a consistent state once more. Information point from 6401.

**Table 5:** Parameters of Each Algorithm

Sr. No.	Algorithms E-Stream	Algorithms HP-Stream
1	Maximum Clustering 10	Num_Clustering 5
2	Stream Speed 100	Stream Speed 100
3	Decay Rate 0.1	Decay Rate 0.1
4	Radius Factor 3	Radius Factor 3
5	Remove Threshold 0.1	
6	Marge Threshold 1.25	
7	Active Threshold 5	

**Efficiency Test:** In this investigation, we set the limits as in Table 5. E-Stream allows the number of gatherings to vary effectively with the constraint of the best number of bundles, anyway, requires a limit on the number of packs. HPStream requires a fixed number of bundles. Since the made dataset has everything thought about five packs in each range, we used five as the (gathering) remembers for HPStream and ten quite far in E-Stream. HPStream requires initial data for its in-statement strategy before beginning stream gathering. We, like this, set it to 100 concentrations to 8000[22].

#### 4.1.5. AWSOM

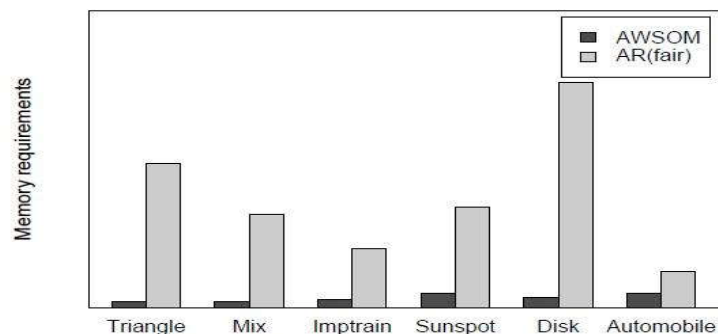
AWSOM stands for Arbitrary Window Stream Modeling Method.

**Table 4:** A brief comparison between traditional data mining and stream data mining

Sr. No.	Datasets	Size	Description
1	Triangle	64K	Triangle waves(Period 256)
2	Max	256K	Square waves (Period 256)Plus sine (Period 64)
3	Impluse	64K	Impulse train (Every 256 points)
4	Arfima	2K	Fractionally difference ARIMA(R package fracdiff)
5	Sunspot	2K	Sunspot data
6	Disk	2K	Disk access trace (fromHewlett-packard)
7	Automobile	32K	Automobile traffic sensor tracefrom large Midwestern state

It is used to discover patterns though remotely. AWSOM is required less number of resources than other clustering techniques. It performs updating in constant time. The space complexity of AWSOM is  $O(\log N)$ . AWSOM algorithms are used for prediction. AWSOM is the technique of Incremental wavelets. Our Experiments are based on real-time and synthetic datasets [23].

AWSOM uses to discover patterns remotely for a long period. We are comparing two techniques, AWSOM and AR. Technique AWSOM is implemented in python language while AR implement in R language[23]



**Figure 11:** Memory Requirements for AWSOM and AR

- **Mining Method:-** This technique of data stream mining.
- **Advantages:-** It is require memory and perform efficiently dynamic updation.
- **Disadvantages:-** Its complexity is too high.

#### 4.1.6. CluStream

It separates the clustering procedure in following two online part and disconnected segments. Online segment stores the rundown of information as small scale bunches. Small scale bunch is the worldly expansion of clustering highlight of BIRCH. Rundown insights of information are put away in previews structure which gives the client adaptability to determine the time stretch for clustering of smaller scale groups. Disconnected segment apply the k-means clustering to bunch small scale groups into greater [24].

CluStream investigates the advancement of bunches by utilizing extra property to remove data of smaller scale groups during a specific time range. Moreover, it applies the inclined time window to upgrade the quantity of put away previews (the status of miniaturized scale groups in the information stream) at contrasting degrees of granularity [24].

**Evaluation** CluStream can make a lot of full-scale bunches for any client specified skyline upon request. Besides, we expect CluStream to be more effective than current calculations at bunching rapidly creating data streams. We will first show the effectiveness and high gauge of CluStream in distinguishing framework interference's[24].

CluStream is that it can make a lot of enormous scope bunches for any customer specified horizon at whatever point upon demand. Additionally, we expect CluStream to be more effective than current calculations at bunching rapidly creating data streams. We will first show the effectiveness and high bore of CluStream in recognizing framework interference's[24]. We contrast the clustering nature of CluStream and that of STREAM for different skylines on various occasions utilizing the Network Intrusion data set. For every algorithm, we decide 5 bunches.

All examinations for this informational collection have shown that CluStream has extensively higher bore than STREAM. Figures 12 (a) and (b) show a segment of our results, where stream speed = 2000 infers that the stream in-flow speed is 2000 centers for each time unit. We note that the Y-rotate is drawn on a logarithmic scale, and along these lines, the overhauls contrast with critical degrees[24].

Presently we look at the exhibition of stream bunching with the Charitable Donation dataset. Since the Charitable Donation dataset only advances a little after some time, STREAM should have the option to bunch this informational index genuinely well. Figures 12 (c) and (d) show the correlation results among CluStream and STREAM. The outcomes show that CluStream beats STREAM even in this case, demonstrating that CluStream is effective for both developing and stable streams[24].

- **Mining Method:-** This technique is used for aggregation micro clustering.
- **Advantages:-** It can quickly resolve concept drift with high accuracy and requires memory.
- **Disadvantages:-** It is offline clustering.

#### 4.2. Classifications

There are the following techniques used for classifications.

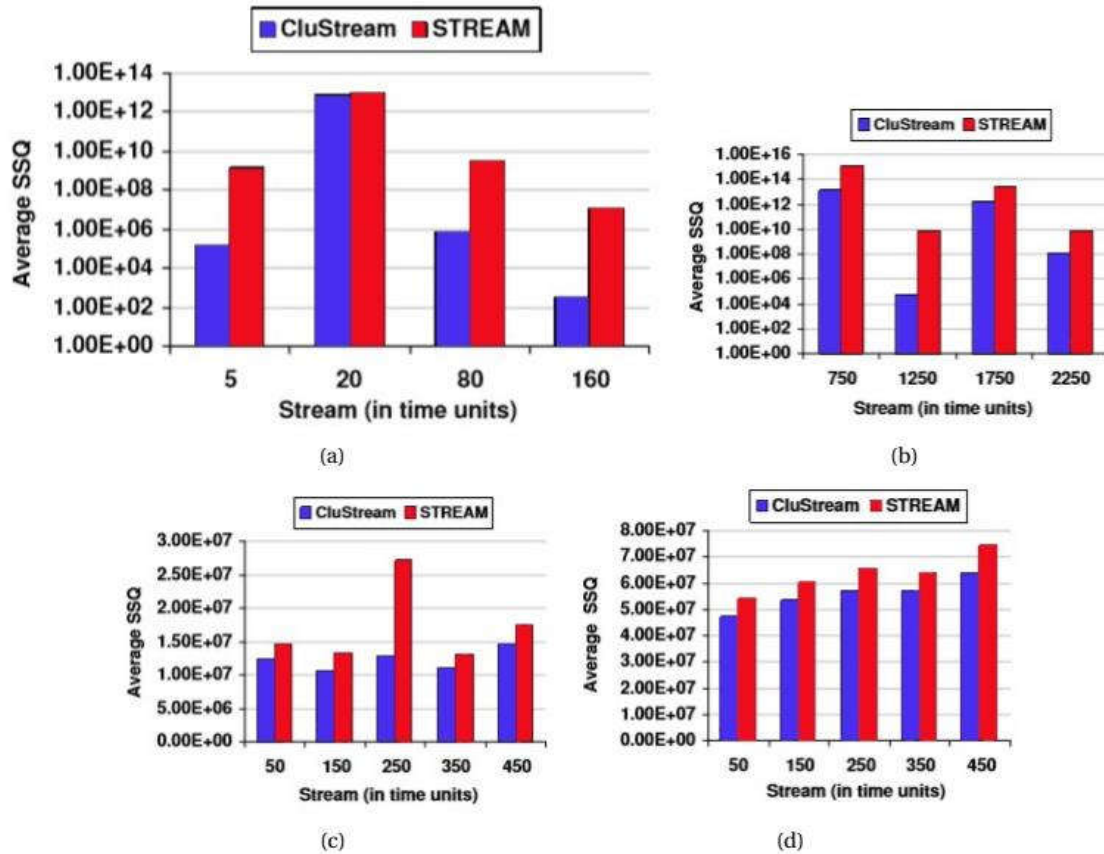
#### 4.2.1. GEMM and FOCUS [25]

**GEMM** stands for Generic model maintenance algorithm. This algorithm Works only where data is rapidly changing with time. It focuses on when we delete records, which is costly compared to inserting new records. This algorithm is used to detect changes between two datasets. It is applied to a logical decision tree. The GEMM algorithm states a model class and an incremental. GEMM is useful in decision trees and determining frequent patterns. GEMM is useful for the sampling model.

**Focus** It is a model that determines how much change in data characteristics with time. Focus algorithms are used to find the difference between the data stream mining model as a deviation in the dataset.

**Mining Method** This technique of data stream mining is used for decision trees and frequent patterns.

- **Mining Method:-** This technique of data stream mining is used for decision trees and frequent patterns.
- **Advantages:-** It can easily resolves concept drift.
- **Disadvantages:-** It can process data at low speed due to complexity.



**Figure 12:** These figures show the different data sets on said labels. In (a) Quality Comparison (Network Intrusion Dataset, Horizon=1, Stream Speed=2000), and (b) shows Quality Comparison (Network Intrusion Dataset, Horizon=256, Stream Speed=200), (c) Quality Comparison (Charitable Donation Dataset, Horizon=4, Stream Speed=200) and (d) shows the Quality Comparison (Charitable Donation Dataset, Horizon=16, Stream Speed=200).

#### 4.2.2. OLIN [16]

**OLIN** stands for online information network. It adjusts continually to the amount of concept drift by the dynamic set scope of the training window. OLIN is applied on recent changes in stream data arbitrary period. OLIN provides higher accuracy than fixed-size sliding windows. OLIN monitors online receiving continuous stream data. OLIN predicts correct classes of receiving stream data by using current classification. OLIN provides correct classification. OLIN uses Information Network (IN) algorithm. Information Network is applied on sliding training window.

OLIN system contains three main modules:

- **Learning Module:-** This module contains implements of an information network which produce information of the fuzzy network.
- **ClassificationModule:-** It use information network classify incoming label class.
- **Meta Learning Module:-** It mange working of Learning Module

Stock market dataset is used in OLIN .stock market dataset contains about 373 companies of data over five year period. OLIN classification predicate next index. For the training we use first 463 records and remain record 5000 are used for validation.



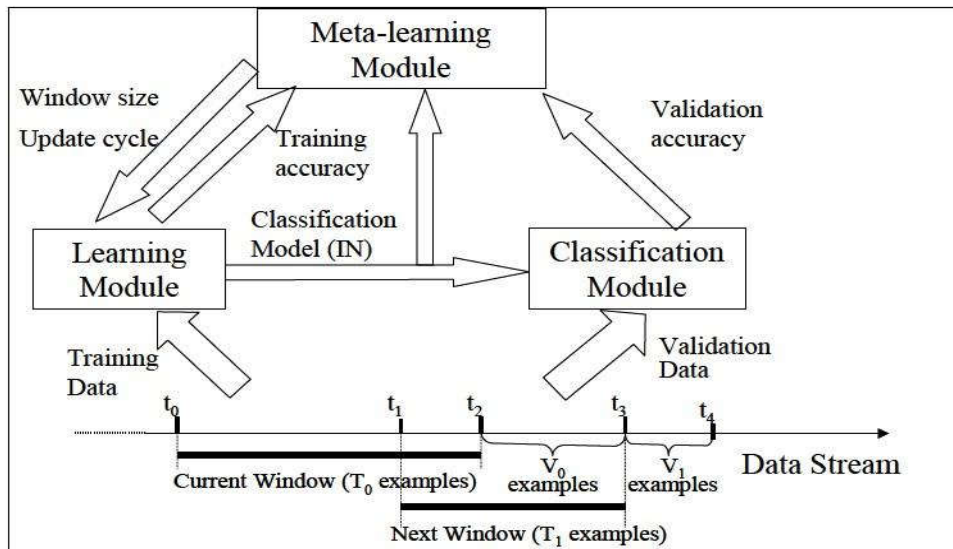


Figure 13: General Procedure OLIN

In above table 7 run 0 indicate there is no training while in 1 to 7 run with training. Each model rebuild with new examples. Figure 14(a) shows stock data with OLIN adjust window size according to concept drift. It shows initial error rate is more significant than when we use concept drift error rate decreases.

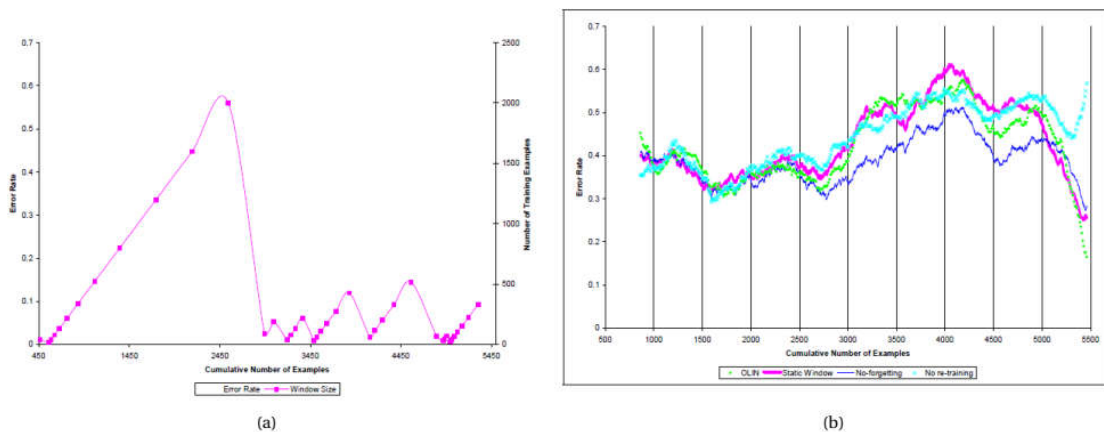


Figure 14: These figures is basically showing the concept drift error rate. In (a) Adjust Concept Drift (b) Comparison of On-line Learners.

Table 6: Stock Data Experiments Results

Run No.	Initial Window	Add Count	Remove Count	Number of Window	Average Window Size	Run Time (Sec)	Error Rate	Variance	P. Values
0	462	500	0	1	5000	1.26	0.450	0.2474	0.000
1	100	100	0	50	2600	18691.07	0.384	0.2364	0.001
2	400	100	0	50	2900	18691.07	0.392	0.2383	0.010
3	400	200	0	25	2900	18691.07	0.398	0.2395	0.042
4	100	100	100	50	100	3.02	0.422	0.2440	0.208
5	400	100	100	50	400	28.78	0.411	0.2422	0.379
6	400	200	200	25	400	15.27	0.423	0.2441	0.180
7	41	Dynamic	Dynamic	41	274	76.90	0.414	0.2427	

Figure 14(b) show different approaches like no retraining and no forgetting. In these figures, calculate all approach error rates with 400 validation records. Accuracy classification is only improved when a computer uses to increase the number of resources. OLIN is better for online classification. OLIN provides better results in adapting new information networks. It provides a low error.

- **Mining Method:-** This technique of data stream mining is used to construct a tree based on classification.
- **Advantages:-** This technique is helpful in dynamic updating operations.
- **Disadvantages:-** This technique allocates more memory, and its performance is not good. The learning process is very costly and time-consuming.



### 4.2.3. VFDT and CVFDT [26]

VFDT stands for a Very fast decision tree. It is based on the Hoeffding decision tree algorithm, attributes of dividing on the base of the threshold. VFDT is a classification technique that is supervised by machine learning algorithms. It is used to discover frequent patterns in pre-processing phase. It uses for decision tree classification. It is used for sampling and is reduced the number of passes in each step. VFDT is used to analyze data synthetic of stream data mining. VFDT works with decision tree classification and is founded on Hoeffding trees. Hoeffding tree is split into the best attribute that contains more information. The algorithm disables minimum auspicious nodes and globules the impossible features. CVFDT is a new version of VFDT.

CVFDT stands for Concept adapting very fast decision tree. It is reliable in terms of identifying patterns with better speed and accuracy than VFDT. CVFDT is useful in the case of discovering one changeable data at each node of the tree. The algorithm works in such a way as to get input current attributes and other attributes. Algorithms replace old sub-tree with new sub-tree due to high information gain. The new sub-tree contains more information and accuracy.

Figure 15 shows a binary classifier containing two classes. Figure (a) indicates two functions of two discriminants, and Figure (b) indicates the log ratio. The first data stream provides high quality than to second one. We use data stream

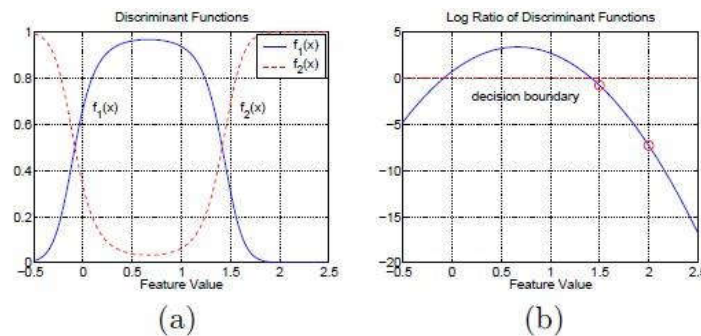
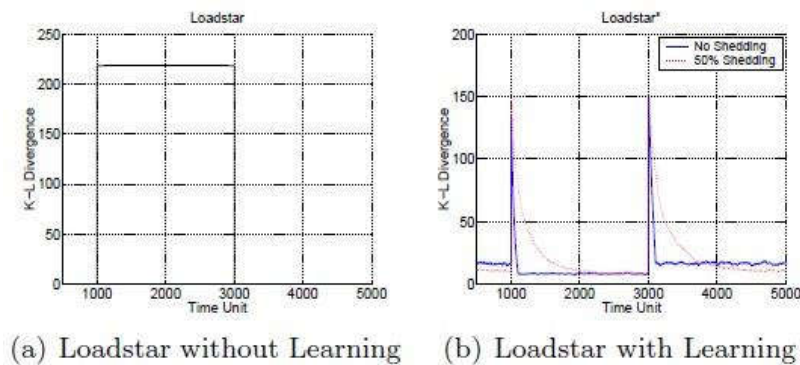


Figure 15: Classification Base Decision loadstar with concept drift. This uses the Markov model that predicts the pattern of unknown data.



**Figure 16:** Loadstar Without Learning and Loadstar With Learning When Loadstar Learning Without Training Accuracy Loadstar learning without training increases the error rate, while Loadstar learning with training decreases the error rate.

- **Mining Method:-** This data stream mining technique uses a decision tree for classification.
- **Advantages:-** This technique requires less memory and high speed.
- **Disadvantages:-** This technique is not deal concept drift.

### 4.2.4. LW Class[27]

LW Cass stands for lightweight classification. LW class is used determining to how many numbers of instances are loaded in the available main memory space. When new classified label data is reached, LW Class searches near instances already in RAM accordingly to the distance threshold. If LW Class determines elements, it checks the class label of elements. If the class label of the element is the same, it increments the weight of that instance. If the element weight is zero, it is deallocated from the main memory. We use Algorithm Output Granularity with LWC for experiments. This experiment measure accuracy.

AOG overhead is constant with a rise in the dataset scope that shows its applicability to refer to such resources in a stimulating environment.

- **Mining Method:-** This data stream mining technique uses class weights for classification.

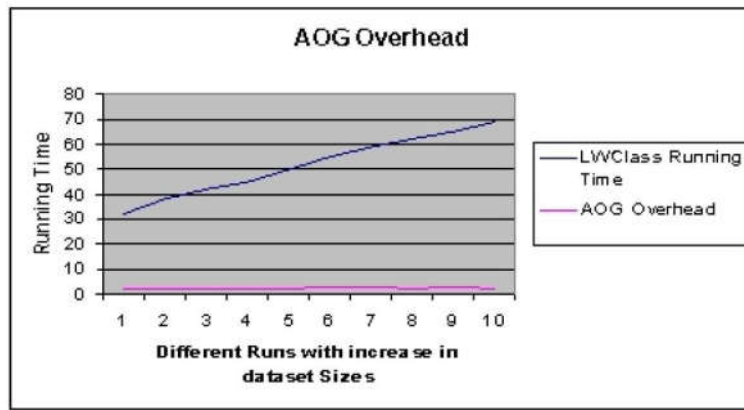


Figure 17: AOG with LWClass

- **Advantages:-** This technique requires less memory and works with high speed.
- **Disadvantages:-** This technique does not deal with concept drift, and learning is time-consuming and costly.

#### 4.2.5. On-demand[28]

On-demand classification builds a new classifier based on past training data. On-demand classifiers provide high accuracy where evolving data streams are. On-demand classification provides accuracy, efficiency, scalability, and sensitivity to stream data.

In order to measure accuracy in On-Demand classification, we study different datasets. It provides high accuracy then other algorithms.

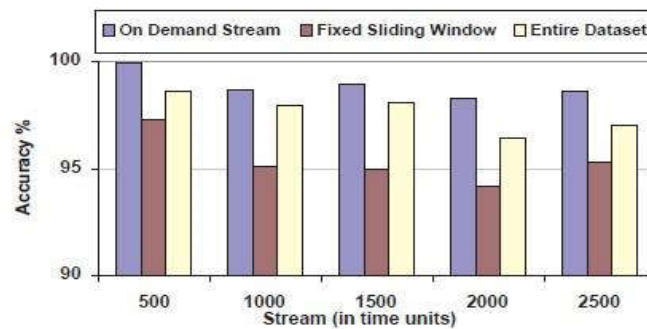


Figure 18: In figure 18 show compare accuracy On-demands classifier with other algorithms. On-demands classifier provides accuracy 4 percentage greater then other algorithms.

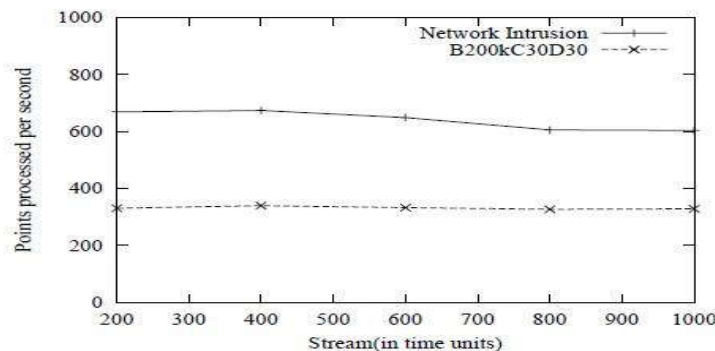


Figure 19: In above figure we use two type of Network Intrusion and synthetic dataset. We can observe that processing rate is slower and after some time it will be stable in both datasets.

- **Mining Method:-** This technique of data stream mining is only class label.
- **Advantages:-** This technique is require less memory and work with high speed in dynamic updation.
- **Disadvantages:-** This technique requires more time for label.

#### 4.2.6. SCALLOP [29]

SCALLOP stands for Scalable Classification Algorithm by Learning Decision Patterns. SCALLOP algorithm attains the stabilization of the models by associating increased limits with each rule. It builds a version of numerous sets of selection policies, one consistent with the set labels. This model has some sets of regulations; we can explain them all brieflyly (1). Example covering: An instance is protected through the guideline by giving space through the defined limits. (2) Positive assist of a rule: the variety of examples blanketed with the aid of the guideline R for Y label are said to be the effective help for R. (3) Negative aid of rule: the variety of examples protected by way of the rule of thumb R for y' label stated to

the negative help of the R. (4) Confidence of rule: Let suppose the positive support is defined as PS as well as the negative support NS, the standard belief rule R could be defined as  $C(R) = PS/(PS+NS)$ . Further, all policies have four factors centrist C, Delimiters D, Markers M, and Growth limits B. Those factors are related to the distinct weights, vectors, limits, and speed through which policies protect examples. The regulations are saved or removed in keeping with several user-described parameters. Positive protecting, viable expansions, and terrible covering are three possible states of affairs for the policies to test the new examples  $e_i = (x_i, y_i)$ . First of all, practical and terrible covering must be checked. If outcomes are false, it directly goes with the viable expansion. The conventional policies are developed with each y fresh example. The y is an operator-described parameter. Two steps are there in refining the model. In the first step, each repetition of dual nearby procedures to each other when their joining together is probable is evaluated. When the union is not possible, the guideline technique will end. The second step encompasses conditions

- Must cover at least one of the remaining study examples.
- High-quality positive support has to be more than or like to the minor support provided by a given operator to keep away from false enlargement that could be involved for dividing soon later SCALLOP appraises the development limits of each one-of-a-kind classified rule  $R_s$  that overlap with  $R_r$  in all dimensions besides one j.

$$\text{Hence If } R_r .I_{jl} > R_s .I_{ju} \text{ then } R_s .B_{ju} \leftarrow \min(R_s .B_{ju}, R_r .I_{jl})$$

$$\text{If } R_r .I_{ju} < R_s .I_{jl} \text{ then } R_s .B_{jl} \leftarrow \max(R_s .B_{jl}, R_r .I_{ju})$$

Classifying innovative questions by elective: Uncertainty new query Q is protected through regulation  $R_q$ , then Q is immediately classified, for example, the label related to  $R_q$ . If no regulation covers the innovative question, SCALLOP deduces the label, which is not viable for Q and is classified through the means of elective. According to the standard procedure, the query is far from the progress bound of all the instructions related to a specific label; this label is excluded from classifying Q. However, if the Q is far from the progress bound of some Y-labeled rule  $R_y$ , the voting goes against Y by one unit. On the contrary, if some T labeled Rule  $R_t$  covers Q, the voting favors T, so the votes of T are improved by one unit. The labels given are with the maximum variety of votes. When two labels have equal votes, the label's distribution decides that this is the class value of the brand-new query.

We generate a decision tree based on eight records, classifier learning randomly.

Each class label has binary values 0 or 1. Table 7 provides results about accuracy and stability. The last tuple shows results about tree changing. After training, 1 million accuracies will be stable. 5 million examples, the number of final laws is a very close number of concepts for learning.

Table 8 displays execution time in seconds. Column TL indicates Table 2 illustrates the outcomes achieved in processing time (seconds). Column TL indicates that the executing time to bring up to date the model is relative as the amount of instances rises, so does the number System stability rises with the number of instances. Columns The UE illustrates that the standard of the rules is getting closer and closer to fundamental ideas to be extracted. Results show that SCALLOP is better for finding a hidden pattern in the data stream.

- **Mining Method:-** SCALLOP classification use only numerical data stream.
- **Advantages:-** This technique is helpful for dynamic updation.
- **Disadvantages:-** This technique is required more memory, and its performance is not good. The learning process is very costly and time-consuming.

#### 4.2.7. ANNCAD [30]

Adaptive NN Classification Algorithm is used for Data streaming. When the data is non-uniform, then ANNCAD is wellknown. In KNN classification K has to be default, so, like the KNN algorithm in general, instead of rusting the number of neighbors, increase the area close to a test point as long as the satisfactory level is achieved. To save calculation time for finding input NN, the first class in each class (cell). To accomplish this, reduce the feature space of a training set and get the representation of multi-dimensional data. Different techniques for representing multi-dimensional data. The ordinary technique used is Haar Wavelets Transformation. ANNCAD contains four leading phases: (1) Quantization of the Features Space; (2) Building classifiers; (3) Discovery predictive class label for exam fact by adaptive finding its adjacent

**Table 7:** Each class label has binary values 0 or 1. SCALLOP classifier learning 128 concepts. Table NE indicates records, CA indicates the accuracy of classification, TC is test records, AC indicates accuracy getting for directed cover, NR indicates rules for classification, NS indicates several rules for dividing data, and RP these rules constructed before processing each label.

Sr. No.	N.E	%CA	%TC	%AC	NR	NS	RP
1	5.104	66.0±0.70	29.2	28.7	189	779	489
2	1.105	4.0±0.40	45.4	45.3	184	1300	1000
3	2.105	84.0±0.17	64.4	64.3	184	2149	2060
4	3.105	91.5±0.15	73.5	73.4	184	2549	3090
5	4.105	93.0±0.11	81.6	81.6	184	3149	4181
6	5.105	94.0±0.10	84.8	84.8	184	3224	5381
7	1.106	95.3±0.01	90.3	90.3	169	3329	12380
8	5.106	95.7±0.01	90.2	90.2	136	4000	72300

**Table 8:** Executing time that classifies ten percentage data. NE shows several records, TL shows the time required to construct the model, TC is classified as time, and UE updates the example.

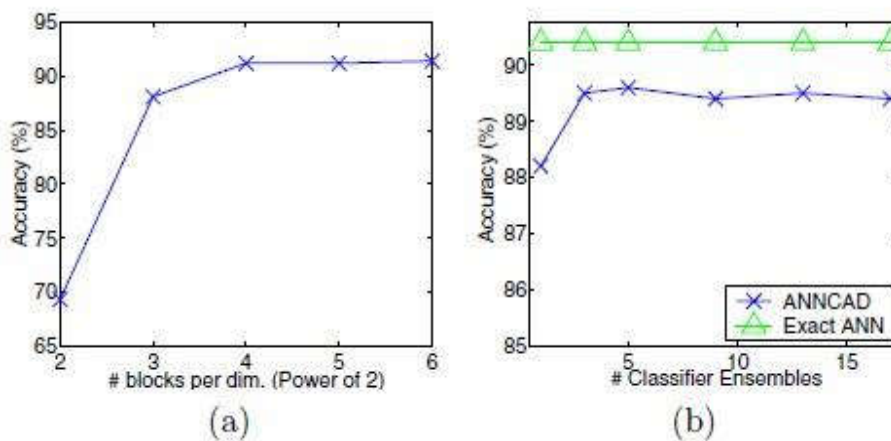
Sr. No.	N.E	NL	TC	UE
1	5.104	64	0.3	41
2	1.105	114	0.5	32
3	2.105	209	1.1	33
4	3.105	249	1.2	17
5	4.105	289	1.5	15
6	5.105	249	1.5	14
7	1.106	339	2.1	5
8	5.106	924	10.7	1

cells; (4) Updating classifiers for recently incoming rows. This technique individual reads each data row at least once and necessitates a little persistent time to process it. We discuss its properties and density.

ANNCAD consists of four main steps: (1) the amount of Feature space, (2) classification; (3) Finding the prognostic label for the test point along the slope of its adjacent cells; (4) Updating the classifiers for new rows. This technique reads individual statistics only once and takes some time to process. When the data is non-uniform, then ANNCAD is well-known. This technique helps to construct multi-dimensional classifiers. We specify different steps to control the efficiency of the classifier. Additionally, there are many optimization constraints on resources and adjusted memory allocation when running on the system. Contrasting VFDT requires massive volume datasets and deciding to enlarge the tree. , ANNCAD does not support it. Comparing it with the time spent in VFDT makes this method more attractive. Additionally, ANNCAD needs one exam to attain this outcome, which illustrates that ANNCAD provides good results on the small data set. ANNCADbased use incremental classification. It reveals a positive change in stream data. ANNCAD classifier is used for incremental classification. Classification is based on the nearest neighbor relation.

In part (a), a better preliminary resolution yields good results. The detail describes that if we start with a better solution, we can reach the limit of the curved decision. This test aims to observe the influence on the different classifiers Pair for ANNCAD .Part (B) shows that combining different classifiers will initially provide good results. When we grow, the number of classifier performances will be improved. We use only 2 or 3 classifications that provide 90.4 percent accuracy in this evaluation.

- **Mining Method:-** SCALLOP classification use only numerical data stream.
- **Advantages:-** This technique is helpful for dynamic updation.
- **Disadvantages:-** This technique requires more memory and offers low speed. The learning process is very costly and time-consuming.



**Figure 20:** Performance evaluation Ensemble classification

#### 4.2.8. Ensemble-SCALLOP ANNCAD based[30]

An ensemble base is an amalgamation of different classification algorithms used for the data stream. In this classification, the data stream is divided into groups on similarity. We can apply different algorithms to each group. When results are obtained for different each group, after this, we choose the best possible results. The ensemble base contains two classifiers, SCALLOP and ANNCAD—Ensemble-SCALLOP ANNCAD, based on Adaptive Nearest Neighbor Classification.

- **Mining Method:-** It uses amalgamation of different type of classifiers.
- **Advantages:-** It resolve concept drift problem with accuracy.his technique is useful for dynamic updation.

- **Disadvantages:-** This technique requires more memory and offers low speed. The learning process is very costly and time-consuming.

#### 4.2.9. CDM [31]

CDM [31] Distance Assessment Framework, Contextual Distance Measurement (CDM) calculates the distance between contexts considering their structure. CDM estimates the distance between the context of the event from the rating in a downward Mode. In each step, the CDM calculates the distance between two instances at the lower level by the total distance of the entities.

Distance between instances: At the grassroots step, CDM essentials a way to relate specific values in the row. By default, the CDM is a commonly used measurement that includes Ecclesiastical distances for numerical attributes (usually in the range [0.1]) and equations for equivalent properties matches. However, additional refined measures can be used since CDM applies these metrics as black boxes. Distance between rows: CDM treats a tuple  $t \mid t$  - uses Euclidean distance to calculate distances between attributes and temples as dimensional vectors. This approach is ordinary for relating rows in a database. Distance between Aspects: One aspect is a collection of tuples. The CDM can employ several similarity measures to calculate the distance between two aspects, including Jaccard's coefficient or Hausdorff distance. In summary, the CDM calculates the distance between two sets of relations at the lower level by summing the distances at the lower level. CDM is also highly satisfactory as it allows domain-specific distances at each level.

- **Mining Method:-** CDM uses two model Decision tree and Bayes network, for classification.
- **Advantages:-** This technique helps measure the distance between instances.
- **Disadvantages:-** This technique offer high complexity.

### 4.3. Prepossessing

Data preprocessing is one of the essential and crucial data mining techniques that transform raw data into a beneficial, understandable format. From the layman's point of view, realworld data is also impropriated, consistent, and complete. As it might be lacking in particular trends or behaviors and is likely to comprise a bundle of errors if we apply our algorithms to such kind of data, it will decrease accuracy. Data preprocessing also plays a pivotal role, as it is a proven method for solving such issues. Data preprocessing is a process of "Detecting" as well as "Correcting or Removing" inaccurate or corrupt records from a database, recordset, or table and referring for further identifying of incomplete, incorrect, inaccurate, or irrelevant parts of given data and at that point adjusting, replacing, changing or deleting the dirty or coarse data. In short, it prepares raw data for further fruitful and meaningful processing. Data preprocessing primarily encompasses of following 5 steps. The first one is "Data Cleaning," the second one is "Data Integration," the third one is "Data Transformation," the fourth one is "Data Reduction," and the fifth as well as last is "Data Discretization." The following are some prominent data-prepossessing techniques.

#### 4.3.1. Sampling

Sampling gains attention when we need to decide whether the processing of probabilistic selection of a data item might be possible or is considered impossible. The sampling technique is preferred in the data stream analysis when the size of the dataset is unknown. So, to find out the error bound, we need to follow a special kind of analysis of our data stream. On the other hand, the second principal con associated with the sampling technique is that it is very important to search for exceptions for the surveillance analysis as an application of data stream mining. In this kind of application, the choice of sampling technique might not be the good one as well as the sampling technique needs to provide the appropriate information for the problems in which the data rate is fluctuating. It is essential to investigate the relationship among the following three parameters in the sampling technique: the Error bounds, the data rate, and the sampling rate.

#### 4.3.2. Load shedding [32]

Load shedding is when the chunks of the data stream have to drop out in a particular sequence. Load Shedding technique greatly impacts querying in the data stream mining process. The problems of this technique and sampling are much more similar. If we have to discuss the drawbacks of load shedding technique, I would like to let you know that when loading shedding is not a favorable option for mining algorithms because it drops out a lot of chunks of data streams that might be the building blocks of the structuring of the generated models as well as these dropped out chunks might be characterizing a pattern of interest in time series analysis. [32, 33]

#### 4.3.3. Sketching [34]

Sketching is the process of randomly mapping a subset of some characteristic. This process is used when the incoming data stream is in a vertical sampling form. Sketching has successfully been implemented compared to several data streams and aggregate queries. The accuracy could be a better advantage of the sketching technique. It is challenging to apply it in the context of data stream mining [34, 35].

#### 4.3.4. Synopsis Data Structures [36]

This kind of data structure is most desirable in which "the update" and "the compute Answer" operations are high-speed. The data stream queries' classification in terms of classes in which there is no exact data structure with the desired properties exists; in these kinds of cases, the best way is to design an approximation data structure that can manage the data stream in the form of small synopsis instead of exact representations that empower it to manage computation per data component to a minimum. The data reduction with the help of synopsis data structures as the best alternative approach of

batch processing sampling has been a very fruitful area of research with appropriate significance for the data stream computation model. Wavelet analysis, frequency moments, quantities, and histograms have been proposed as synopsis data structures in this field.

#### **4.3.5. Approximation Algorithms [37]**

The roots of approximation algorithms belong to the algorithm design. This technique is suitable and more inclined toward designing algorithms for computationally challenging problems. These algorithms provide the solution with an approximation that has error bounds associated with it. The basic idea behind this is that the mining algorithms are assumed to be computationally challenging problems provided with their three main features. The first one is "continuity," the second one is "speed," and the third one is "the generation of the environment" that has been further characterized by resource-constrained. Most researchers have been attracted to approximation algorithms since the early 21's century because they look at this as a straightforward and optimal solution for the major problems of data stream mining. Although, the approximation algorithms could not provide the appropriate solution for the data rate about the available resources. In order to provide the solution to this problem of adaption of available resources, you must use other tools along with these approximation algorithms. Muthukrishnan, S Chawla [37] has also used an approximation algorithm in his excellent research paper.

#### **4.3.6. Sliding windows**

Sliding windows is one of the essential techniques for producing an approximate answer to data stream queries when you want to assess the queries not over the entire history of the data streams, rather than you want only to focus the sliding window over the recent data from the streams. For instance, the previous week's data might be considered for producing query answers, whereas the data earlier than the one week is discarded. Performing sliding windows over the data streams is a popular way of producing approximations with many appealing properties. The sliding window has been practiced as one of the essential tools for approximation in terms of faces of bounded memory. It also averts stale data from influencing statistics and analysis. This area of reach is fully developed, although only a few reaches have been carried out on extending summarization techniques to sliding windows. Some of the recent work has been briefly described here. M Datar et al. [38] have fully described in their technique how sketching is utilized for computing the  $L_1$  or  $L_2$  norm as well as they pour their gaze on maintenance of simple statistics over sliding windows with full acknowledgment. This technique requires a multiplicative space overhead of  $mO(E \log N)$ . Here E represents the accuracy of the parameter, whereas the sliding window's length is represented by N. This technique is the way to convert the sketching-based algorithms into the sliding windows model. Their research also provides space lower bounds for numerous issues in the sliding windows model. Furthermore, Motwani, M Datar, and Babcock, in their other research work [39] opted for the sampling algorithm as a reservoir for the sliding windows model as well as in another attempt of their research in the field of data streams, Motwani and GS Manku [40] also shown that their techniques adapt their algorithms as a sliding window model. S Guha and Koudas [41] as well as in their earlier research work with the collaboration of K Shim[42] have adopted techniques for maintaining V-Optimal Histograms on the classified data streams as a sliding window model; however, their algorithm requires the buffering for all the elements present in the sliding window. Following are some open problems for sliding windows: the first one is "maintaining statistics like variance," the second one is "clustering," the third one is "maintaining top wavelet coefficients," and the fourth one is "computing correlated aggregates" [43].

#### **4.3.7. Algorithm Output Granularity (AOG) [27]**

The first well-known resource-aware data analysis approach is none other than the algorithm output granularity (AOG). The AOG approach can deal with high data rates with fluctuation, as per available memory and the processing speed denoted by time constraints. It is a very suitable approach for regional data analysis on devices with constraints regarding resources. These resource-constrained devices generate or receive streams of information simultaneously and continuously. The "algorithm output granularity (AOG)" approach has three main stages. The very first stage is "adaptation to resources"; the second stage is represented by "data stream rates" for mining, whereas the third stage is represented by "merging the generated knowledge structures when running out of memory." For the last two decades, AOG has been implemented as a core part of many domains like classification, clustering, and frequency counting citegaber2005board. The functionality of the AOG algorithm has shown in Figure 21.

### **5. Comparison of different techniques of data stream mining**

In recent years, different data stream mining techniques have been developed for classification and clustering. We study types of different techniques, basic on preprocessing and nonpreprocessing. In classification, that saves memory for mining. In this section, we Comparison between different techniques of classification and clustering.

**Table 9:** A brief comparison between different kind of classification techniques.

Sr. No.	Classification Techniques	Mining operation	Pros	Cons
1	GEMM and FOCUS	Decision tree and recurrent element sets item sets	<ul style="list-style-type: none"> <li>• Detect Concept drift</li> <li>• Incremental model</li> </ul>	Time overwhelming and expensive learning
2	OLIN	Usages info fuzzy approach's for classification model	<ul style="list-style-type: none"> <li>• Dynamic Updation</li> </ul>	<ul style="list-style-type: none"> <li>• Slow speed</li> <li>• Time overwhelming and expensive learning</li> </ul>
3	VFDT and CVFDT	Decision Trees	<ul style="list-style-type: none"> <li>• High speed</li> <li>• Require less memory space</li> </ul>	<ul style="list-style-type: none"> <li>• It does not work with concept drift</li> <li>• Time overwhelming and expensive learning</li> </ul>
4	LWClass	Classes Weights	<ul style="list-style-type: none"> <li>• High speed</li> <li>• Require less memory space</li> </ul>	<ul style="list-style-type: none"> <li>• It does not work with concept drift</li> <li>• Time overwhelming and expensive learning</li> </ul>
5	CDM	Bayes network	It use to measure distance between events	complexity
6	On-Demand Stream Classification	Using micro-clusters ideas that each micro-cluster is associated with a specific class label which defines the class label of the points in it.	<ul style="list-style-type: none"> <li>• Dynamic update</li> <li>• High speed</li> <li>• Need less memory space</li> </ul>	High cost and time need for labeling
7	Ensemble-Based Classification	Using combination of different classifiers	<ul style="list-style-type: none"> <li>• Single pass</li> <li>• Dynamic update</li> <li>• Concept drift adoption</li> <li>• High accuracy</li> </ul>	<ul style="list-style-type: none"> <li>• Low Speed</li> <li>• Storage memory problem</li> <li>• Time consuming and costly learning</li> </ul>
8	ANNCAD	Incremental classification	<ul style="list-style-type: none"> <li>• Dynamic update</li> </ul>	<ul style="list-style-type: none"> <li>• Low Speed</li> <li>• Storage memory problem</li> <li>• Time consuming and costly learning</li> </ul>
9	SCALLOP	Scalable classification for numerical data streams	<ul style="list-style-type: none"> <li>• Dynamic update</li> </ul>	<ul style="list-style-type: none"> <li>• Low Speed</li> <li>• Storage memory problem</li> <li>• Time consuming and costly learning</li> </ul>

In recent years, there have been different data stream mining developed that are used to discover knowledge from large amounts of data for analysis and to make a decision. Some techniques only work on one phase, and others cannot. Below is some technique used for different phases of stream data 2. mining.

#### 1. Detecting frequency patterns with pre-processing.

##### (a) Clustering

- Stream and Local Stream [18]
- VFKM [10][18]
- CLustream [24]

##### (b) Classification

- GEMM and FOCUS [25]
- OLIN [16]
- VFDT and CVFDT [26]
- LW Class[27]
- On-demand[44]4.
- Ensemble-SCALLOP ANNCAD based [30]

#### 2. Detecting frequency patterns without pre-processing. (a) Clustering

- D-Stream [45]
- HP Stream [7]
- AWSOM [23]

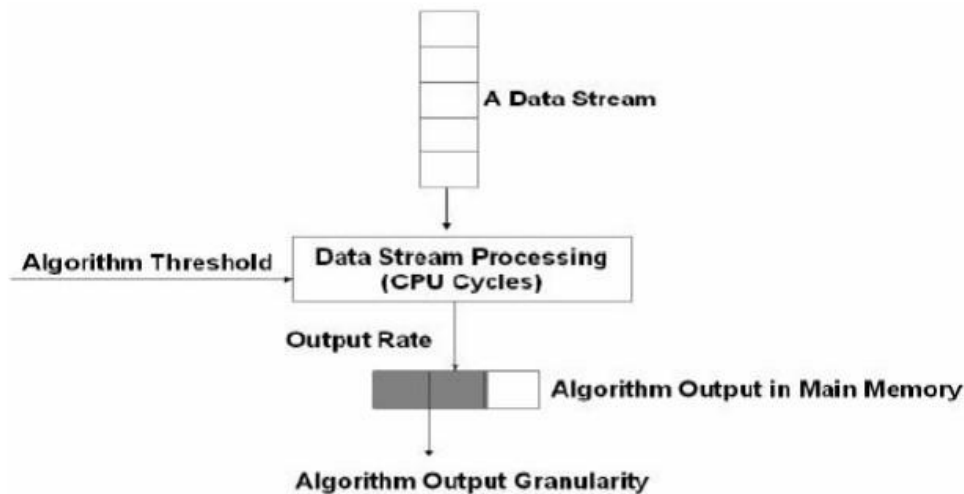
##### (b) Classification

- SCALLOP [29]
- ANNCAD [30]
- CDM [31]

### 3. Time Series Analysis and frequency counting

- Approximate Frequent Counts [40]
- FP Stream [46]

### 4. Pre-processing techniques for Stream data mining [47]



**Figure 21:** Function of Algorithm Output Granularity [27]

#### a) Store some portion of concise data

- Sampling
- Load shedding
- Sketching

#### b) Choosing a subset of incoming stream

- Synopsis data
- Aggregation

#### c) Without needing to store

- Approximation Algorithms
- Sliding windows
- Algorithm Output Granularity

LOCAL SEARCH and STREAM are clustering algorithms [18]. It provides good feature data stream clustering. It is a combination of two algorithms, STREAM and local search. It is used for incremental learning. STREAM is used to find the scope sample and apply LOCAL SEARCH. If the sample size is large, then apply the built-in equation. This procedure is repetitive for each portion of data. Lastly, LOCALSEARCH is applied in the cluster center that generated preceding iterations.

VFKM [10][18] is a clustering technique that is used to discover frequent patterns in the preprocessing phase of stream data mining. It is an unsupervised machine-learning algorithm. It implements by the k-means clustering algorithm. VFKM is used for sampling and reduces the number of passes in each step. This technique is used to analyze data synthetic of stream data mining—k-means clustering algorithms to group binary data streams. K-means is used to group the entire data sets and synthetic data sets. K-means is the management of group data and the removal of data redundancy.

GEMM and FOCUS [25] algorithms are used to detect changes between two datasets. It is applied to a logical decision tree. The GEMM algorithm states a model class and an incremental. GEMM is helpful in decision trees and determines frequent patterns. GEMM is beneficial for the sampling model. Focus algorithms are used to find the difference between the data stream mining model as a deviation in the dataset.

OLIN [16] stands for online information network. It adjusts continually to the amount of concept drift by the dynamic set scope of the training window. OLIN is applied on recent changes in stream data arbitrary period. OLIN provides higher accuracy than fixed-size sliding windows. OLIN monitors online receiving continuous stream data. OLIN predicts correct classes of receiving stream data by using current classification. OLIN provides correct classification. OLIN uses Information Network (IN) algorithm. Information Network is applied on sliding training window.



**Table 10:** A brief comparison between different kind of clustering techniques.

Sr. No.	Clustering Techniques	Mining operation	Pros	Cons
1	Stream and Local Search	It uses K Medians	Step by step learning	<ul style="list-style-type: none"> <li>• Low quality</li> <li>• Low accuracy</li> </ul>
2	VFKM	It uses K Medians	<ul style="list-style-type: none"> <li>• Efficient speed</li> <li>• Require less memory</li> </ul>	Multiple passes
3	CluStream	it works with microclustering approach.	<ul style="list-style-type: none"> <li>• Efficient speed</li> <li>• Require less memory</li> <li>• It works with concept drift</li> </ul>	Offline clustering
4	D-Stream	Density based clustering	<ul style="list-style-type: none"> <li>• High quality</li> <li>• High speed</li> <li>• It works with concept drift</li> </ul>	High complexity
5	AWSOM	It predicts pattern	<ul style="list-style-type: none"> <li>• High quality</li> <li>• High speed</li> <li>• Require less memory</li> </ul>	High complexity
6	HPStream	It works with projection	<ul style="list-style-type: none"> <li>• High dimensional</li> <li>• Incremental update</li> <li>• High scalability</li> </ul>	High complexity

VFDT[26] is a classification technique that is supervised by machine learning algorithms. It is used to discover frequent patterns in the preprocessing phase. It uses for decision tree classification. It is used for sampling and is reduced the number of passes in each step. VFDT is used to analyze data synthetic of stream data mining. VFDT works with decision tree classification and is founded on Hoeffding trees. Hoeffding tree is split into the best attribute that contains more information. The algorithm also disables the minimum auspicious leaves and drops the impossible attributes. CVFDT is a new version of VFDT. CVFDT is useful in the case of discovering one changeable data at each node of the tree. The algorithm works in such a way as to get input current attributes and other attributes. Algorithms replace old sub-tree with new sub-tree due to high information gain. The new sub-tree contains more information and accuracy.

LW Cass [27] stands for lightweight classification. LW class is used determining to how many numbers of instances are loaded in the available main memory space. When new classified label data is reached, LW Class searches near instances already in RAM accordingly to the distance threshold. If LW Class determines elements, it checks the class label of elements. If the class label of the element is the same, It increments the weight of that instance. If the element weight is zero, it is deallocated from the main memory.

On-Demand [28] classification is used to build a new classifier based on past training data. On-Demand classifiers provide high accuracy where evolving data streams are. On-Demand classification provides stream data's accuracy, efficiency, scalability, and sensitivity.

Ensemble-SCALLOP ANNCAD[30] based on Adaptive Nearest Neighbor Classification. Ensemble-SCALLOP ANNCADbased use incremental classification. It reveals a positive change in stream data.

D-Stream [45] is stand for Density-Based Clustering. Densitybased clustering has been for some time proposed as another significant clustering technique—density-based clustering structure for information streams. Using density-based switching over K-mean algorithms for data streams takes work. There are two significant technical challenges. First of all, it is not appropriate to present the data series as a long series of static data because we are interested in the evolving sophisticated features of the data stream. To overcome the dynamic change of clusters, we propose an innovative scheme that combines a decaying element with the density of each data point. In addition, D-Stream does not require the user to specify the number of clusters k. Thus, D-Stream is particularly suitable for users with low domain information on user data. Second, due to the large amount of stream data, it is impossible to maintain density information for each data record. Therefore, we suggest dividing the data space into irrational gr n grids and mapping new data records in a similar grid. Therefore, we do not need to retain the raw data and only work on the grid. The algorithm maps each input data to the grid, calculates the density of each grid, and clusters the grid using a density-based algorithm. D-Stream automatically and dynamically adjusts the clusters without requiring user specification of the target time horizon and the number of clusters. The experimental results show that D-Stream can find clusters of arbitrary shapes. Compared to CluStream, D-Stream is better in terms of both clustering quality and efficiency, and it exhibits high scalability for large-scale and high-dimensional stream data. The method makes fast information stream clustering doable without corrupting the clustering quality. It is a natural and attractive basic clustering algorithm for the density method of data streams. It can handle noise. It can find arbitrarily shaped clusters. This scan algorithm only needs to test the raw data once. Furthermore, it does not require prior information on the number of clusters because the Kresource algorithm does. We test and compare the clustering speed of D-Stream and CluStream. The total stream requires four to six times more clustering time than the D-

stream. DStream client because it puts every new data through the online component on the same grid as it does computing distances without a clear stream.

HPStream [45] stands for high projection. It is used to determine the frequent patterns in data. It determines changes and updates datasets of each part of the transaction and timesensitive patterns. HPStream clustering technique that is used to discover frequent patterns without preprocessing phase of stream data. Unsupervised learning algorithms are used for high-data dimensional stream data because this clustering quality could be better. For this problem, we chose those subset-relevant dimensions close to clustering. We select active clusters that contain samples that express the characteristics of each other cluster. Active cluster is expanded rapidly. That is why the action cluster is not similar to inactive clusters.

AWSOM [23] stands for Window Stream Modeling Method. It uses to discover patterns through sensors. The space complexity of AWSOM is  $O(\log N)$ . AWSOM algorithms are used for prediction. AWESOME is technique Incremental wavelets?

SCALLOP algorithm [29] attains the stabilization of the models by associating increased limits with each rule. It builds a version of numerous sets of selection policies, one consistent with the set labels. This model has some sets of regulations; we can explain them all briefly. Example covering: By giving space through the defined limits, the instance is protected through the guideline. Positive assist of a rule: the variety of examples blanketed with the aid of the guideline R for Y label are said to be the effective help for R. Negative aid of rule: the variety of examples protected by way of the rule of thumb R for y' label stated to the negative help of the R. Confidence of rule: Let suppose the positive support is defined as PS as well as the negative support NS, the standard belief rule R could be defined as  $C(R) = (PS/PS+NS)$ . Further, all policies have four factors centrist C, Delimiters D, Markers M, and Growth limits B. Those factors are related to the distinct weights, vectors, limits, and speed through which policies protect examples. The regulations are saved or removed in keeping with several user-described parameters. Positive protection, viable expansions, and terrible covering are three possible states of affairs for the policies to test the new examples  $e_i=(x_i, y_i)$ . First of all, effective and terrible covering must be checked. If outcomes are false, it directly goes with the viable expansion. The set of policies is refined with each new Y example. The y is a user-described parameter. Two steps are there in refining the model. In the first step, every iteration, the two nearest rules to each other when their union is possible are analyzed. When the union is not possible, the guideline technique will end. The second step encompasses conditions that must cover at least one in every of the remaining study examples. High-quality positive support has to be greater than or equal to the minimum support provided by a given user to keep away from false enlargement that could be involved in splitting shortly after SCALLOP updates the growth bounds of every one-of-a-kind classified rule  $R_s$  that overlap with  $R_r$  in all dimensions besides one j. Hence

**If  $R_r .Jjl > R_s .Jju$  then  $R_s .Bju \leftarrow \min(R_s .Bju, R_r .Jjl)$**

**If  $R_r .Jju < R_s .Jjl$  then  $R_s .Bjl \leftarrow \max(R_s .Bjl, R_r .Jju)$**

Classifying new queries by voting: If new query Q is protected by means of rule  $R_q$  then Q is immediately classified as the label related to  $R_q$ . If there is no rule that covers the new question, SCALLOP tries to deduce the label which is not viable for Q, and it has classified by means of voting. According to the standard procedure, the query is far away from the growth bound of all the rules associated with a specific label; this label is rejected to classify Q. However, if the Q is far away from the growth bound of some Y-labeled rule  $R_y$ , the voting goes against Y by one unit. On the contrary to it, if some sort of T labeled Rule  $R_t$  covers Q, the voting goes in favor of T, so the votes of T are increased by one unit. The labels assigned are those with the highest variety of votes. When two labels have equal votes, the label's distribution decides that this is the class value of the brand-new query.

Versatile NN Classification Algorithm [30] is used for Data streaming. At the point when the information is non-uniform, then ANNCAD is notable. In KNN characterization K must be the default; in this way, similar to the KNN calculation, rather than rusting the number of neighbors, increment the territory near a test point as long as the good level is accomplished. To spare estimation time for discovering input NN, five stars in each class (cell). To accomplish this, at that point, diminish the component space of a preparation set and get the portrayal of multi-goal information. There are numerous methods for speaking to multi-goal information. The normal procedure utilized is Haar Wavelets Transformation. ANNCAD incorporates four fundamental stages:

1. Quantization of the Feature Space.
2. Building classifiers.
3. Finding a prescient name for a test point by adaptively finding its neighboring cells.
4. Updating classifiers for recently showing up tuples.

This calculation reads every tuple at most once and requires a little steady an ideal opportunity to handle it. We, at that point, talk about its properties and multifaceted nature. ANNCAD comprises four fundamental advances: (1) the measure of Feature space, (2) grouping; (3) Finding the prognostic mark for the test point along the slant of its neighboring cells; (4) Updating the works of art for new tuples. This calculation peruses every measurement just a single time and sets aside some effort to measure. We, at that point, talk about its highlights and unpredictability. At the point when the information is non-uniform, then ANNCAD is notable. This calculation makes it simple to manufacture multi-goal classifiers. Clients can determine the number of levels to efficiently control the fineness of the classifier. Besides, one may improve the framework asset limitations and alter the fly when the framework runs out of memory. Unlike VDFT, which requires a

huge informational collection to conclude whether to grow the tree by one more level, ANNCAD doesn't have this limitation. This strategy is more appealing by contrasting the time spent in VFDT. Also, ANNCAD needs one sweep to accomplish this outcome, which shows that ANNCAD even functions admirably for a little preparation set.

Separation Assessment Framework [31], Contextual Distance Measurement (CDM), which figures the separation between settings remembering their structure. CDM gauges the separation between the setting of the occasion from the rating in a descending way. At each level, the CDM computes the separation between two substances at the lower level by the absolute separation of the elements. The separation between Attributes: At the grassroots level, CDM needs an approach to look at singular qualities in Tuples. Of course, the CDM utilizes an ordinarily utilized estimation incorporating Ecclesiastical separations for mathematical traits (as a rule in the range [0.1]), and conditions for identical properties match since CDM applies these measurements as secret elements, more complex measures can be utilized. The separation between Tuples: CDM treats a tuple  $t$  | With one  $t$  | - Uses Euclidean separation to compute separations among qualities and sanctuaries as dimensional vectors. This methodology is standard for looking at tuples in an information base. The separation between Aspects: One angle is an assortment of tuples. The CDM can utilize various comparability measures to compute the separation between two viewpoints, including Jaccard's coefficient or Hausdorff's separation. In Synopsis, the CDM figures the separation between two arrangements of relations at the lower level by adding the separations at the lower level. CDM is additionally profoundly good as it permits explicit area separations at each level.

Approximate Frequent Counts[40] is used to determine frequent patterns in data. It determines changes and updates datasets of each part of the transaction. This algorithm is used to count frequencies exceeding user-specified data stream limits. This algorithm is simple and has small memory marks. Although the output is approximate, the error is guaranteed not to exceed the user-specific parameters. The algorithm can be easily applied to singleton items found in IP network monitors. It can also handle rivers of variable size sets of goods, for example, through a series of market basket transactions at the retail store. For such a series, we describe the implementation of a better optimization for repeatedly counting item sets in a pass. This algorithm will accept two userspecific parameters: a support threshold and an error parameter. The answers generated by our algorithm will have the following guarantees: 1. All items (sets) whose actual frequency is greater than  $N$  are the outputs. There are no false positives. 2. An item (set) whose actual frequency  $N$  is not less than  $N$ . 3. The estimated frequency is mostly lower than the actual frequency. Our algorithm has two aspects of proximity: (a) high-frequency false positives and (b) small errors in individual frequencies. Both types of errors in applications are tolerable. We say that if the algorithm maintains the edeficient symposium, its output fulfills the abovementioned features. We aim to develop an algorithm to support e-deficient Synopsis using as little memory as possible. A well-known technique for estimating frequency count works on uniformly random sampling. The algorithm calculates the exact count in two directions. The algorithm can handle a lower cost of help threshold than before. This is also practical in a moderate central memory environment. The algorithm provides a practical solution to the problem of gradually maintaining the rules of association in the layout of the warehouse.

Sampling refers to the procedure of choosing whether or not a data item will be processed. The issue is the Unknown dataset size by the sample in the framework of data stream inquiry. It does not identify a problem in Variation data.

The Load shedding procedure in which reducing the order of the data stream is called Load shedding. It is used in inquiring data streams. It is challenging to have load shedding used with mining algorithms as it consists of a series of data pieces that can be used in its structure. Developed models or this time series may represent a pattern of concern in the inquiry.

Sketching is the method of creating a subgroup of a random feature. This is a vertical sampling process upcoming stream. It has been applied to the comparison of different streams.

Synopsis data uses summary techniques that are capablesummarizing the upcoming streams' further analysis, such as Wavelet analysis, histograms, quantiles, and frequency. It provides an approximate answer because it can not represent the full features of the dataset.

Aggregation is a data mining algorithm used to input data stream represented as summarized form. It could be more efficient in the case of Fluctuation data distributions.

Approximation Algorithms are one-pass algorithms used to create approximation results according to an Adequate error margin. Approximation algorithms are used in the complicated problem.

Sliding windows is pre reprocessing technique used to analyze the most recent stream data mining.

Algorithm Output Granularity algorithms are used where limited time and memory are for stream data mining. The threshold is a control parameter that contains distance that manages the data transfer rate based on the output rate.

## 6. Data stream mining Applications

**StreamQuery** In fast growing development applications generated different type of data stream such cameras generate video streams. Data stream mining has numerous applications across various domains. One notable application is Stream

Query, which involves querying and analyzing high-volume data streams in real time. This application is particularly relevant in IoT (Internet of Things) and Fog computing architectures.

One example of a Stream Query application is Gigabit, which utilizes Fog architecture. Gigabit is an Internet-scale repository system that handles crowd-sourced video streams generated by different cameras. The primary objective of Gigabit is to avoid transmitting massive video streams over the backbone Internet.

In the Gigabit system, video-processing tasks such as categorization and segmentation are performed at a Virtual Machine (VM)-based Cloudlet within the associated Metropolitan Area Network (MAN). The Cloudlet processes video streams locally, extracting relevant video metadata. Only the video metadata is transmitted to the Cloud, where it can be stored and indexed for Internet-wide SQL searches on the catalog. This architecture allows for efficient network bandwidth utilization by reducing the amount of video data transmitted over the Internet. By processing video streams at the edge of the network, within the Cloudlet, only the necessary metadata is sent to the Cloud for further analysis and querying.

Stream Query applications like Gigabit demonstrate data stream mining techniques to handle and analyze large-scale data streams efficiently, especially in scenarios where realtime processing, bandwidth optimization, and distributed architectures are essential.

## 7. Conclusion

In this paper, we reviewed and analyzed essential data mining techniques that face challenges in real-time applications. Different data mining techniques are classified data streams into classification and clustering. In this paper, data stream mining classification techniques are VFDT, CVFDT, CDM, On Demand-Stream classification, ensemble-based classification, and ANNCAD, that appropriate and practicable for data stream mining. In contrast, other techniques GEMM, FOCUS, OLIN, and SCALLOP, are unsuitable for data stream mining. Data stream mining clustering techniques are VFKM, CluStream, AWSOM, and HPStream are applicable for data stream mining. Then we examine the evaluation of different data stream mining results that some techniques are feasible for the realtime data stream and some of not. This study provides a complete understanding of techniques and their benefits. Despite the research on data mining techniques in data stream mining, there is still a wide area for further research.

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